

An Effective QoS based Route Optimization Model in MANET using Machine Learning

M. Janardhan, Prof. S. Pallam Shetty, Prof. Prasad Reddy P.V.G.D

Department of Computer Science & Systems Engineering, Andhra University, Visakhapatnam, India

ABSTRACT

Mobile Ad hoc network is a network which is dynamic where the mobile nodes form a temporary network in the deficiency of centralized administration, i.e. A MANET is an autonomous group of distributed mobile nodes. Due to the absence of centralized administrator in a network, routing in mobile ad hoc network (MANET) becomes the primary issue which reduces the selection of an optimal path for routing. Specific performance parameters such as latency, overhead, and packet delivery ratio (PDR) are affected unfavorably for which various techniques such as Machine Learning approach are encouraged that enhances the selection of the efficient and stable path. In our, Proposed Research works our attempt is made to select the optimal route i.e. which supports to identify the pattern for Link failure in communication and Optimized routing path for better communication to achieve the QoS for MANET environment using knowledge-based learning algorithm. The optimal path will possess the highest average sum of relay nodes and will be considered as the most optimal and reliable path. We also anticipated that analysis of throughput and PDR is better as compared to the traditional methods.

Keywords : Routing Protocols, Internal Attacks, External Attacks, Manets

I. INTRODUCTION

There are research contribution exist in routing mechanisms of MANETS by considering the QoS parameters.

- ✓ Ant Colony Based QoS Routing Algorithm for Mobile AdHoc Networks is an on-demand QoS routing algorithm [1] proposed by P.Deepalakshmi. This algorithm is adaptive in nature and reduces the end to end delay in high mobility cases. But the other QoS constraints i.e. other network layer or link layer metrics like energy, jitter, link stability etc. are not considered here. Furthermore, here link failure is not handled properly.
- ✓ Metrics in Mobile Ad Hoc Networks proposed by R. Asokan [2] and it performs well in route discovery phase with dynamically changing topology and produces better throughput and low delay variance. Again flooding of route request may potentially reach all nodes in the network, so bandwidth wastage increases and efficiency degrades. Besides this, it is a collision and contention prone routing protocol. Thus, packet delivery ratio decreases, congestion increases and throughput also become very poor in case of multimedia. The routing overhead is also increased.
- ✓ An on-demand routing protocol Ant-E [3] is introduced by Srinivas Sethi which is based on Blocking Expanding Ring Search (Blocking-ERS) to control the overhead and local retransmission to improve the reliability. It resumes its route Discovery process to discover a route to the destination node from the place where it ended in

the last round following a failure. More energy is consumed because of this routing process.

- ✓ S.Kannan has projected a multi agent ant based routing algorithm for MANET [4]. It is a hybrid algorithm which combines the concepts of multi agents and ant algorithm. This technique increases node connectivity and decreases average end to end delay and increase packet delivery ratio. But complex optimization problems are not considered in algorithm.
- ✓ B. R. Sujatha has proposed a PBANT algorithm [5] which optimizes the route discovery process by considering the position of the nodes which can be obtained by GPS receiver but here energy parameter is not taken into account.

Routing Protocols:

Initially, the optimization property of ACO algorithms has attracted much attention. Inspired by it, researchers have been motivated to apply ACO algorithms to find optimized routes for network communications. There are many approaches that belong to this category. Here we present the most famous ones in chronological order.

AntNet

Di Caro and Dorigo [30] have proposed AntNet, which is the first representative ACO-based algorithm for solving the problem of internet routing. In AntNet, each node proactively sends out Forward ANTs (FANTs) to discover a path to a randomly chosen destination node. Once FANTs reach the destination, Backward ANTs (BANTs) are sent back to the source node following the reverse path. BANTs update the local models of the network status and the local routing table at each intermediate node. The performance of AntNet is evaluated in three different wired network scenarios.

ARA

Another representative ACO-based routing protocol for MANETs, ARA was proposed by Günes et al. [31]. ARA is an on-demand routing algorithm, which is based on a simple ant colony optimization meta-heuristic algorithm. The whole routing algorithm consists of three phases: a route discovery phase, a route maintenance and a route failure handling. The route discovery phase in ARA is designed in a similar way to AntNet. FANTs and BANTs are used in the route discovery phase. FANTs are broadcasted by the sender. Duplicate FANTs are identified by their sequence numbers and are deleted by intermediate nodes. Once FANTs reach their destination nodes, BANTs are created and sent back to the source nodes. Different from AntNet [30], ARA uses data packets to maintain the route to avoid the overhead caused by using periodic ants. If a node recognizes a link failure, it first sets the pheromone value of this link to zero to deactivate it. Then it searches for an alternative link. If this fails, it informs its neighbors. This process is repeated until an alternative route has been found or the source node receives a route error message. In the latter case, the source node will initiate a new route discovery phase if there are still packets to be sent.

PERA

Baras and Mehta [32] have proposed PERA, a proactive routing protocol. PERA uses ant-like agents to discover the network topology and maintain routes in dynamic networks such as MANETs. PERA uses three kinds of ants: regular FANTs, uniform FANTs and BANTs. Regular and uniform FANTs are sent out proactively. These ants explore and reinforce available routes in the network. Uniform FANTs are routed in a different way than regular FANTs. Instead of using the routing table at each node, uniform FANTs choose the next hop node with uniform probability. Uniform FANTs help avoid that previously discovered paths become overloaded. BANTs are used to adjust the routing tables and statistic tables at each node, according to the information gathered by FANTs. The

authors have compared PERA with AODV [2]. The results indicate that PERA has lower delay in all cases. However, the throughput of PERA at the higher speed is slightly less than AODV and the goodput of PERA is lower than AODV in high mobility scenarios.

AntHocNet

Di Caro et al. [33] have presented a hybrid multi-path routing algorithm, AntHocNet. In AntHocNet there are 6 different kinds of ants: Proactive FANTs (PFANTs), Proactive BANTs (PBANTs), Reactive FANTs (RFANTs), Reactive BANTs (RBANTs), RePair FANTs (RPFANTs) and RePair BANTs (RPBANTs). In the reactive route setup process, if a source node has no routing information about the requested destination node, it broadcasts RFANTs. Otherwise, it unicasts. When this RFANT reaches the destination, a RBANT is sent back to the source. Along its journey, the RBANT collects quality information about each link in the path and updates the pheromone table at each intermediate node. Once the First route is constructed, AntHocNet starts the proactive route maintenance process. Here, source nodes send out PFANTs to their destination nodes. PFANTs consider both regular and virtual pheromone for choosing the next hop node at each intermediate node. Once a PFANT reaches the destination node, it is converted to a PBANT. PBANTs update the regular pheromone table on their way back to the source node. In case of a link failure, RPFANTs and RPBANTs are used to handle the problem. The authors have implemented the protocol in QualNet [34] and investigated its performance using various simulations and comparing the results to AODV [2].

PACONET

Osagie et al. [35] have proposed an improved ACO algorithm for routing called PACONET. In PACONET, a source node reactively broadcasts FANTs in a restricted manner to explore the network. Each FANT records the total time it has traveled and maintains a list of all visited nodes. At each intermediate node the

FANT updates the pheromone value. Once a FANT arrives at the destination, a corresponding BANT is generated. The BANT uses the list of visited nodes recorded by the FANT to travel back to the source node. Along the way, the BANT also updates the pheromone value in the reverse direction. Different from the AntNet, PACONET let both FANTs and BANTs update the pheromone. The performance of PACONET has been compared with AODV [2]. The results show that PACONET has less end to end delay and routing control overhead than AODV, but the packet delivery ratio is nearly the same.

ACO-AHR

Yu et al. [36] have proposed a hybrid routing algorithm ACO-AHR, which includes reactive routing setup and proactive routing probe and maintenance. There are two kinds of agents: ant agents and service agents. The ant agents are FANTs and BANTs as in other ACO based routing algorithms. In the reactive routing setup process, a source node broadcasts FANTs. Along the trip, each FANT records all the nodes it has visited in order to avoid cycles in the path. Each BANT carries all the information collected by the corresponding FANT. It calculates the delay from one intermediate node to the destination node. Once a BANT ant reaches the source node, a service agent is created. The service agent updates the routing table at intermediate nodes by using the information gathered by the BANT. In the proactive routing maintenance process, proactive FANTs are sent out while the data session is ongoing. The proactive FANTs are normally unicasted, but they could be broadcasted with a small probability. In the latter case, the FANTs may be able to find new paths.

HOPENT

HOPENT is proposed by Wang et al. [37]. It is based on the zone routing framework, combined with an ACO algorithm. HOPENT performs local proactive route discovery within a node's neighborhood and reactive communication between neighborhoods.

HOPENT is simulated on GlomoSim [38] and the authors have compared HOPNET with several famous routing protocols, such as AODV [2], AntHocNet [33], and ZRP [39]. The results indicate that HOPNET is highly scalable for large networks in comparison with AntHocNet [33]. Moreover, the author also varied the zone radius in the experiments and results indicate that the selection of the zone radius has considerable effect on the performance.

ANT-E

Sethi and Udgata [40] have proposed an ACO-based on-demand routing protocol Ant-E. Ant-E uses Blocking Expanding Ring Search (Blocking-ERS) [41] to limit overhead and controls local retransmission to improve the Packet Delivery Ratio (PDR). The authors compared Ant-E with AODV [2] and DSR [3]. The results show that Ant-E performs better.

OUTLINE :

Here we have introduced some of the representative protocols which were proposed in the early stage of ACO based routing protocols. The First ACO based routing protocol, AntNet, proposed in 1998, gave a good example of how to apply the ACO algorithm in communication networks. In the following ten years, many subsequent researchers proposed various ACO based routing protocols for MANETs based on this idea. Protocols in this category aimed for Finding the optimal routes in dynamically changing networks and their performance indicated that ACO is a promising solution for routing problems in MANETs. This further encouraged researchers to design novel ACO based routing protocols which consider other issues, such as Quality of Service (QoS), energy consumption and so on.

Table 1. Design parameter overview of basic ACO routing protocols.

Protocol	Routing Approach	Tran. Type	FANT	Ph. Activator
AntNet [30]	proactive	unicast		BANTs
ARA [31]	reactive	broadcast		FANTs, BANTs, DPs
PERA [32]	proactive	unicast		BANTs
AntHocNet [33]	hybrid	both		RBANTs, PBANTs
PACONET [35]	hybrid	broadcast		FANTs, BANTs
ACO-AHR [36]	hybrid	both		service agents
HOPENT [37]	hybrid	unicast		FANTs, BANTs
Ant-E [40]	reactive	broadcast		FANTs, BANTs, DPs

TABLE 2. Pheromone parameter overview of basic ACO routing protocols.

Protocol	Design Goals	Ant Types	Pheromone	
			Reinforcement	Evaporation
AntNet [30]	distributed, robust, multi-path routing	FANT, BANT	goodness of trip time	goodness of trip time
ARA [31]	reduce overhead	FANT, BANT	hop count	constant rate
PERA [32]	reduce overhead	FANT, BANT, uniform FANT	delay, hop count, trip time	delay, hop count, trip time
AntHocNet [33]	efficient routing	PFANT, PBANT, RFANT, RBANT, RPFANT, RPBANT	hop count, delay	constant rate
PACONET [35]	efficient dynamic routing	FANT, BANT	travel time, run time parameter	constant rate
ACO-AHR [36]	apply multi-agents to reduce expense	FANT, BANT	travel time, ant release ration	constant rate
HOPENT [37]	high scalability, less overhead	IFANT, EFANT, BANT, NANT, EANT	travel time	constant rate
Ant-E [40]	control overhead, improve reliability	FANT, BANT	hop count	constant rate

QoS AWARE ACO ROUTING PROTOCOLS

QoS has always been a focus of attention in mobile ad hoc networks. It is a challenging problem when transmitting packets via multiple paths in a dynamic network. At the same time, the pheromone concept from ant colony algorithms also inspires many authors to use QoS parameters for selecting routes.

1) ARAMA

ARAMA is an early proactive routing algorithm proposed by Hussein and Saadawi [42]. The FANTs in ARAMA gather both local and global path information, which could be the Quality of Service (QoS) parameters such as the remaining battery energy, delay, numbers of hops, etc. ARAMA defines a local normalized link index which is a good measure for overall path information. Once the FANT reaches the destination, the path grade is calculated based on this path index. A BANT follows the reverse path to the source node and updates the pheromone table at each hop.

2) SAMP-DSR

SAMP-DSR is proposed by Khosrowshahi-Asl et al. [43], which aims to solve the shortcomings of both ACO and DSR [3] algorithms. In SAMP-DSR, each node can operate in two modes, called 'local mode' and 'global mode'. Depending on the rate of network topology change, nodes switch between the two modes, in order to help the ants converge efficiently.

3) QAMR

QAMR is a QoS-enabled ant colony based multipath routing protocol for MANETs which is proposed by Krishna et al. [44]. It selects paths based on Next Hop Availability (NHA) and the path preference probability. The NHA is defined as the availability of nodes and links for routing on a path, considering both mobility and the energy factors. In order to find the best path that satisfying the QoS constraints, QAMR uses a path preference probability which measures different parameters such as delay, bandwidth and hop count. However, there are many extra control messages for estimating the quality of outgoing links.

4) QoRA

Al-Ani and Seitz [45] have introduced a QoS Routing protocol for multi-rate ad hoc networks based on Ant colony optimization (QoRA). In order to reduce the overhead when collecting information from multiple paths and to avoid congestion during data transmission, this paper uses the Simple Network Management Protocol (SNMP) [46] to estimate QoS parameters locally. The proposed mechanism consists of two components: the QoRA entity and the SNMP entity. The QoRA entity runs on every node to identify a suitable route that meets the specified QoS requirements, while the SNMP entity collects detailed information about the characteristics of the outgoing links such as bandwidth, delay and packet loss. More specifically, the QoRA entity consists of five components: the neighbor table, the routing table, the

ant Management, the decision engine and the QoS manager. While the two tables are common components of a routing protocols, the other three components are specially designed for QoRA. The ant management is responsible for generating FANTs, BANTs and EANTs, all of which contain specific information necessary to provide QoS-aware routing and to identify pheromone deposits. The QoRA decision engine is a vital part which decides which of the different ants are to be sent and which updates the neighbor and routing table. The QoS manager acts as a command generator and notification receiver application. It also calculates QoS parameters locally based on communication with the SNMP entity. QoRA consists of five phases regarding route discovery and route maintenance. The first phase is the forward phase. The source node broadcasts a FANT to the network to find the best route to the destination. Before forwarding the packets, each intermediate node checks the FANTStack to avoid loops and whether the given QoS requirements are satisfied. In the packet forwarding phase, intermediate nodes read the flow information and randomly forward the packets based on a probability roulette-wheel selection scheme [47] using the data in its routing table. The Backward phase starts after the destination node receives FANTs. The destination node calculates the residual QoS values and sends a BANT back to its neighbors. The BANT collects route quality information, refreshes the routing table, updates the pheromone and computes the QoS threshold. The Monitoring phase is mainly used for avoiding congestion problems by monitoring decreasing transmitting speeds. For each flow, QoRA communicate with the SNMP entity to calculate QoS parameters locally. If the required QoS is not satisfied in a certain period time (MonitoringWindow), the affected node broadcasts an EANT to inform the previous nodes about the congestion problem. When a node detects the loss of a link to a neighboring node, it deletes the information about this neighbor node from the neighbor table and updates the route table

by Finding an alternative path using EANTs. The QoRA protocol does not require either exchanging additional control packets or synchronizing nodes with the help of the SNMP entity. It computes QoS parameters locally to reduce overhead. The computation of QoS parameters is all loaded to the SNMP entity which allows the QoRA protocol to reduce end-to-end delay. Although it is clear that the QoRA entity requires less overhead, the communication between the QoRA entity and SNMP entities consumes more energy and bandwidth.

OUTLINE : Here we discussed five representative protocols which focus on QoS fulfillment. QoS has always been a vital task for data transmission in MANETs. The approaches focus mainly on the parameters: link stability and hop count. Other common QoS related improvements are a reduction in overhead produced by control messages and the ability to eschew the requirement of time synchronization. Many other QoS parameters such as link delay, remaining battery energy, end to end reliability and bandwidth are treated as pheromone reinforce factors in above protocols.

Quality of Service is the primary mission for data transmission and communication in MANETs.

TABLE 1.Design parameter overview of QOS aware ACO routing protocols.

Protocol	Routing Approach	Tran. Type	FANT	Ph. Activator
ARAMA [42]	proactive	unicast	BANTs	
SAMP-DSR [43]	hybrid	unicast	RREQs	
QAMR [44]	reactive	broadcast	BANTs, FANTs	
QoRA [45]	reactive	broadcast	BANTs	

TABLE 2. Pheromone parameter overview of QOS aware ACO routing protocols.

Protocol	Design Goals	Ant Types	Pheromone	
			Reinforcement	Evaporation
ARAMA [42]	Optimize hop counts and QoS, energy efficient	FANT, BANT	queue delay, remaining battery energy, link's signal to noise ratio, bit error, path grade	path grade
SAMP-DSR [43]	Solve the shortcoming of ACO and DSR	FANT, RREQ	end to end reliability, the trip time	unknown
QAMR [44]	Achieve link stability	FANT, BANT	bandwidth, delay, hop count	constant
QoRA [45]	less further control messages or without synchronization	FANT, BANT, EANT	constant	constant

TABLE 3. Pheromone parameter overview of energy aware ACO routing protocols.

Protocol	Design Goals	Ant Types	Pheromone	
			Reinforcement	Evaporation
ACO-EEAODR [48]	increase network lifetime	RREQ, RREP	remaining battery power	unknown
EAAAR [49]	less energy consumption, multi-path transmission	FANT, BANT	MBR, hop count	constant rate
AntHocMMP [50]	path robustness, extend network lifetime	FANT, BANT	energy path cost	constant rate
ACECR [51]	extend network lifetime	FANT, BANT	avg. & min. energy, hop count	constant rate
Hybrid ACO [52]	secure, energy efficiency	FANT	predefined constant	constant rate

SECURITY AWARE ACO ROUTING PROTOCOLS

Other than QoS and energy efficiency, security is another hot topic in routing protocols which attracts many researchers' attention. As is well-known there exist many security threats in the network layer, such as black hole attacks, wormhole attacks, Flooding attacks and so on. When these attacks are launched during the routing process, this usually leads to strong harmful effects on the network. In the worst cases, an attacker might even make the communication in the network impossible. Therefore, mechanisms that help participants in a network to defend against the potential attacks are necessary. However, the scope of security is wide. Different researchers have their own ideas about how to best build defense systems. In this section, an overview about existing security aware ACO based routing protocols is presented.

1) SAR-ECC

Vijayalakshmi and Palanivelu [62] have proposed a secure ant based routing algorithm for cluster based ad hoc networks using Elliptic Curve Cryptography (ECC [63]), which we abbreviate as SAR-ECC from here on.

This approach makes use of two basic processes: one is estimating the trust value between neighbor nodes. The other uses the AntNet routing mechanism for route discovery and ECC for mutual authentication between the source and destination. In the network, each node in the cluster keeps trust values for all its neighbors. A trust value is calculated based on a measurement of uncertainty and is an increasing function that correlates with the probability of successfully transmitting each packet. During route establishment, the source node tries to find multiple routes using AntNet [30]. Then it gathers the trust values of all nodes in the paths. Based on the trustworthiness of nodes, it selects a trustworthy route for data transmission. The novelty of the protocol is using a trust value based on a measurement of uncertainty instead of the conventional pheromone. However, the updating mechanism for the trust value is not described and the benefits of combining a cluster structure with an ACO algorithm are not clearly described.

Due to the prevalence of security threats in the networks, security is also a hot topic that attracts many researchers' attention. Common attack types are, for example, black hole and wormhole attacks. Different researchers have proposed various ideas about how to ensure security in their routing protocols. In this section, we compare a selection of security aware ACO based routing protocols. These protocols use several methods to ensure secure routing. From Table 4, we observe that all surveyed protocols in this subsection use reactive approaches, thus avoiding the higher overhead commonly associated with proactive methods. For example, besides the regular proactive routing table maintenance, if a malicious node is detected in proactive approaches, all nodes in the network need to put the malicious node into black lists and update their routing tables to avoid routes including the reported malicious node. Table 5 shows that most of the security aware ACO routing protocols aim to ensure finding secure and reliable

routes. Some of them such as DBA-ACO [73] and ANTNET [74] focus on defending against certain attack types, while others are interested in detecting malicious or anomalous nodes in the network. All the listed protocols use the basic ant types, except ABPKM [75] which has two other special ant types, namely Repair ANTs (RANTs) and Update ANTs (UANTs). Although some of the proposed protocols have not described their pheromone related parameters clearly, we can still observe that there are various pheromone reinforcement factors, which are applied in this subsection. Besides a trust value, which is the most common parameter, there are also other parameters used for reinforcing the pheromone values, such as traveling time, distance, trails and attractiveness. In contrast to the reinforcement factors, most of the protocols use a constant rate to evaporate the pheromone over time. From these research contributions it is clearly evident that still the scope exists for proposing a routing mechanism by achieving the QoS parameter such as delay, jitter, scalability, performance, throughput, energy consumption etc.

TABLE 4. Design parameter overview of security aware ACO routing protocols.

Protocol	Routing Approach	Tran. Type	FANT	Ph. Activator
SAR-ECC [62]	reactive	unicast		unknown
SPA-ARA [64]	reactive	both		BANTs
FTAR [71]	reactive	broadcast		FANTs
SBDT [72]	reactive	unknown		unknown
DBA-ACO [73]	reactive	unknown		unknown
ANTNET [74]	reactive	unknown		ANTs
ABPKM [75]	reactive	unicast		BANTs

TABLE 5. Pheromone parameter overview of security aware ACO routing protocols.

Protocol	Design Goals	Ant Types	Pheromone	
			Reinforcement	Evaporation
SAR-ECC [62]	secure routing	FANT, BANT	trust value	unknown
SPA-ARA [64]	energy efficiency, detect malicious nodes	FANT, BANT	distance, traveling time	constant rate
FTAR [71]	trusted routing	FANT, BANT	constant rate	constant rate
SBDT [72]	detect malicious nodes	FANT, BANT	unknown	unknown
DBA-ACO [73]	detect and prevent black hole attack	FANT, BANT	unknown	unknown
ANTNET [74]	detect and prevent black hole attack	ANT	trails, attractiveness	unknown
ABPKM [75]	secure self-organized authentication routing	FANT, BANT, RANT, UANT	trust value	constant rate

Table 6. Simulation parameter overview of ACO based routing protocols.

	Protocol	Compare with	Simulator	DDR	Delay	Overhead	Special
Basic	AntNet [30]	OSPF,SPF,BF, Q-R,PQ-R, Daemon	own simulator [30]	NO	YES	YES	YES
	ARA [31]	AODV, DSRV,DSR	NS2 [78]	YES	NO	YES	NO
	PERA [32]	AODV	NS2	NO	YES	NO	YES
	AntHocNet [33]	AODV	QualNet [34]	YES	YES	YES	YES
	PACONET [35]	AODV	GloMoSim [38]	YES	YES	YES	NO
	ACO-AHR [36]	AODV	NS2	YES	YES	YES	NO
	HOPENT [37]	AODV,ZRP, AntHocNet	GloMoSim	YES	YES	YES	YES
	Ant-E [40]	AODV,ZRP, AntHocNet	NS2	YES	YES	YES	NO
	ARAMA [42]	without	OPNET [79]	YES	NO	NO	YES
	SAMP-DSR [43]	EMP-DSR,MP-DSR, AODV,AntHocNet	OMNet++ [80]	YES	YES	YES	NO
QoS aware	QAMR [44]	AODV, ARMAN	NS2	YES	NO	YES	YES
	QoRA [45]	AODV, CLWPR	NS-3 [81]	YES	YES	NO	YES
	ACO- EEAODR [48]	EEAODR	GloMoSim	NO	NO	NO	YES
Energy aware	EAAR [49]	AODV,MMBCR, AntHocNet	GloMoSim	NO	NO	NO	YES
	AntHocMMP [50]	AntHocNet,LAR, R-ACOLMMP	NS2	YES	YES	YES	YES
	ACECR [51]	AOMDA, EAAR	NS2	YES	YES	NO	YES
	Hybrid ACO [52]	Normal ACO	unknown	NO	YES	NO	YES
Security aware	SAR-ECC [62]	without	NS2	NO	NO	NO	YES
	SPA-ARA [64]	AODV,DSR,ARA	SWANS [85]	NO	NO	NO	YES
	FTAR [71]	ANT-U	NS2	YES	YES	YES	YES
	SBDT [72]	CAPMAN	NS2	YES	YES	NO	YES
	DBA-ACO [73]	without	NO	NO	NO	NO	NO
	ANTNET [74]	without	NS2	NO	NO	NO	YES
	ABPKM [75]	without	QualNet	YES	YES	YES	YES

Routing Protocols:

Some of the representative protocols which were proposed in the early stage of ACO based routing protocols. The First ACO based routing protocol, AntNet, proposed in 1998, gave a good example of howto apply theACO algorithm in communication networks.In the following ten years, many subsequent researchers proposed various ACO based routing protocols for MANETs based on this idea. Protocols in this category aimed for Finding the optimal routes in dynamically changing networks and their performance indicated that ACO is a promising solution for routing problems in MANETs. This further encouraged researcher to design novel ACO based routing Protocols which consider other issues,

such as Quality of Service (QoS), energy consumption and so on.

QoS AWARE ACO ROUTING PROTOCOLS :

QoS has always been a vital task for dat transmission in MANETs .The proposed method was a new energy and delay-aware routing protocol that combines cellular automata (CA) with the hybrid genetic algorithm (GA) and African Buffalo Optimization (ABO) to optimize the path selection in the ad-hoc on-demand distance vector (AODV) routing protocol.

AN EFFICIENT ENERGY AND DELAY ROUTING PROTOCOL :

Our proposed research attempt to establish a robust path and get fulfill the QoS requirement as energy and delay. Our research comprised two stages to achieve our objective,

The proposed method was a new energy and delay-aware routing protocol that combines **cellular automata (CA)** with the **hybrid genetic algorithm (GA)** and **African Buffalo Optimization (ABO)** to optimize the path selection in the ad-hoc on-demand distance vector (AODV) routing protocol.

In the first stage we used CA to discover all possible paths based on minimum time, the second stage selects the path based on highest energy level for each node in the path by using **hybrid algorithm GAABO**. We proposed **hybrid techniques** that will enable the discovery of routes in MANETs which satisfy both the delay constraints and some simple energy constraints (every node on a path has a minimum energy level). Aforementioned, the **CA** generate the paths from source to destination nodes based on the minimum delay, the RREQ message that sends by CA content a threshold term to ensure all paths achieve the requirement of delay. Subsequently, the Hybrid Algorithm Gaabo.

Discovering Routes by CA

To find out a path with delay as the QoS constraint. There exists no hierarchy among the nodes, and the network plane is found to be fully homogeneous (i.e. all nodes consist of the same characteristics). Our approach involves the broadcasting of the RREQ message that constitutes the delay requirement of the connection request [maximum delay (D_{max})] by the source node to its communicating neighbors. All the nodes at the right, left, top, and down side are involved in this, as depicted in Figure 2.

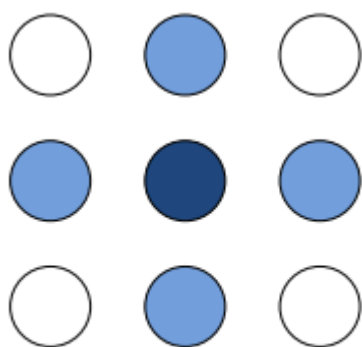


Figure 2: CA mechanism

The message re-broadcast by the intermediate nodes to their neighbors, which also establish a reverse path to the sender. Certain nodes, when given a delay constraint, turn into a wave, take in a wave node to their neighbors, re-broadcast the message, and establish a reverse path to the nodes from which they had obtained the message. This activity continues till the message is collected by the destination node or the delay faced by the packet outstrips the limit D_{max} . The destination obtains many RREQ messages for the same sender when there are more paths from the sender to the destination. Consequently, reply to some of the RREQ messages is done by the destination through sending an RREP message through the reverse path that is established when the RREQ messages are passed on. The entire set of nodes observed along these routes amidst the source and the destination constitute the path nodes. Each and every communication between the source and the

destination from this juncture happens through this path till the topology of the network gets modified.. Algorithm for two-way dimensional of CA for the initial and shortest path.

- i. Input the radius of the CA $K=1$;
- ii. Put loop for the loop for discovering and checking loop for checking both side route from sn-dn and dn-sn
- iii. checking the neighbours of CN node ,which $[r,c]= \text{find}(O == CA)$
- iv. storing path created by nag node with concatenating original sn node
- v. concatenating dn to created path

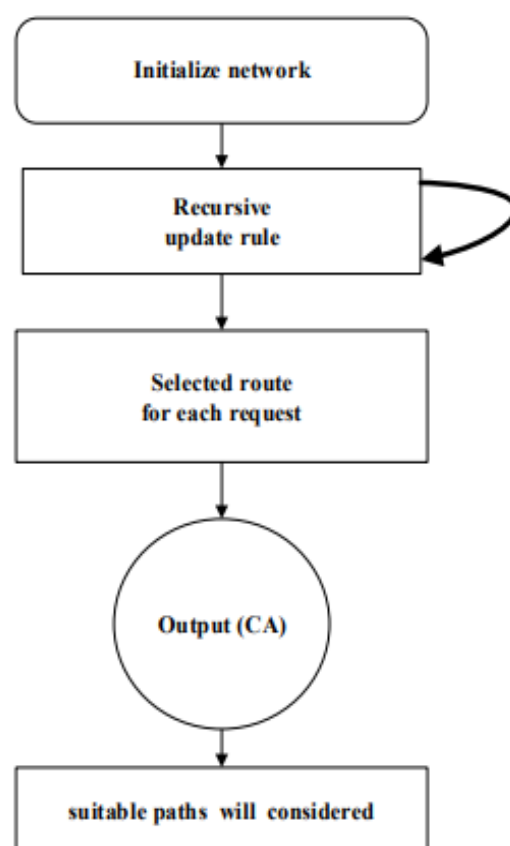


Figure The Process rule for short path selection

A. hybrid GAABO with CA:

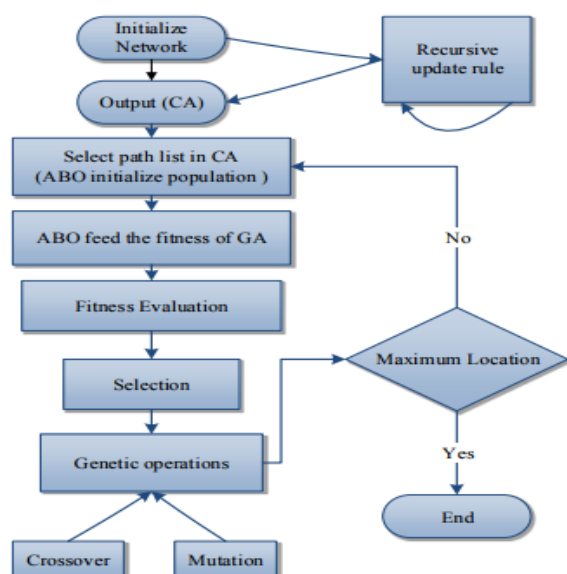


Fig : The process of CA with hybrid algorithm

Backbone Based Quick Link Failure Recovery Multicast Routing Protocol :

An Efficient Backbone Based Quick Link Failure Recovery Multicast Routing Protocol is a hybrid protocol with the features of tree based and mesh based routing protocols. The proposed protocol overcomes the limitations of existing protocols. It has four phases: Group Formation, Backbone Construction, On-Demand Route Discovery and Route Maintenance. At the inception every node exchange HELLO packets with the neighbour nodes and compute 1- hop neighbouring count, the node which possess the highest count of 1-hop neighbor nodes will be elected as the core node and send core request to 1-hop neighbouring cores. Upon receiving reply from neighbouring cores backbone will be formed. When a source intends to transmit data packets firstly it checks its route cache if route found directly transmits data packets to destination. Else initiate the route discovery process and once route is found multicast data packets. In the transmission path of data packets if any link failure is encountered, upstream node initiates route discovery to generate an alternate path towards destination.

The main aim of the proposed protocol is to construct an efficient robust backbone to overcome the limitations of existing protocols and to provide a mechanism for the quick recovery of link failures by generating an alternate path from the point of failure to the destination, which can be adoptable in any sort of environment.

Energy Efficient Routing based on Route Segmentation :

The proposed energy efficient routing based on route segmentation (EER-RS) provides a scalable and energy saving routing model for MANETs. This maintains small route segments for the active routes. The functionality of route discovery of EER-RS is comparable to DSR where multiple routes are discovered to reach the target node, and the shortest and optimal route is used for routing. In the case of longer routing, the shortest route might have a few hops to reach the target node. These hops, when segmented into w node, make v route segments. The process of construction segmentation is described below.

Route Segmentation Mechanism:

The intention of segmenting route is to make EER-RS scale for the bigger network. The distribution of network in MANET is into regions based on the node ranges as shown in Fig.1. The two highlighted node in the figure makes a 2-hop segment. One can decide the number of hops based on the route hops length.

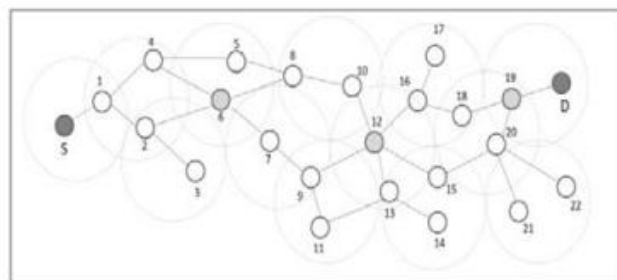


Figure 1: A general network with regions and 1-hop nodes

Let's consider a route discovery process of node S, identifies two prominent routes to reach D as shown below.

Route1: S→1→4→6→8→10→12→16→18→19→D

Route2: S→1→2→6→7→9→12→15→20→19→D

If the segment length, $w=2$, then each route will be divided w segments having a segment head which maintain the segment path to reach segment end node as shown in Table-1.

Table 1: Node Segment routes

S	6	12	19
1→4→6	8→10→12	16→18→19	D
1→2→6	7→9→12	15→20→19	

The advantage of these route segment supports in low energy utilization in maintenance in case of broken links. It can be present locally at the stage of a segment. Fixing a failure route within a segment broadens the life span of the route and accumulate energy through minimizing frequent route discoveries process. Thus, this mechanism will substantially help in reducing the routing overhead and energy consumption and improve the performance. Even varying segment length, w can support the adaptive routing scheme, which will be important for MANETs. Utilizing these segments we compute the minimum energy required to route data over it which will save the energy further.

Energy Saving Mechanism:

Even though segmenting route save quite an amount of energy through minimizing routing overhead, but is essential to route data in an energy efficient route. As mention in Table-1 that each node in a route maintains its own segment path, eventually identifying the best energy sufficient path for routing can make the segment life longer and throughput efficiency can be achieved. To compute the energy level of each segment path we enhance the algorithm

CMMBCR [24] ("Conditional Min-max Battery Capacity Routing") which recognize the routes that have an adequate left over energy of a battery and then choose the routes with lowest total transmission power .

Let's represent a routing structure by a graph $V = (N, E)$, where, N is "the set of nodes" and E is "the set of communication edges".

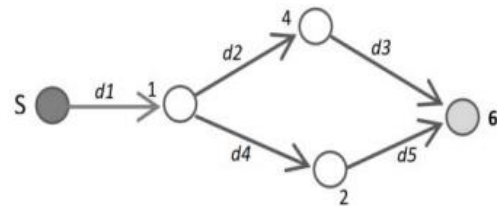


Figure 2: A graph model of node S to reach Node-6
Based on fig.2, the node S has to send a packet to N6, which has two paths to reach and the energy needed to send a message to each hopping node is directly comparative to the square of its distance. If the first path distance, $p1$ have a distance is, $p1=(d1+d2+d3)$ then the energy required for transmitting is, $e1=(p1)^2$. Since, node S also have another path for transmitting and its distance is, $p2 = (d1+d4+d5)$, and its energy required is, $e2 = (p2)^2$. In this case, if $e1 \geq e2$ then, S transmit data through $p2$ instead of $p1$ to save energy.

The minimum energy, B required between nodes S to next node n to send the message can be computed using the equation-1 as follows,

EER-RS Based Routing Mechanism :

In EER-RS, the nodes in the primarily discovered path are selected as segment end point based on the configured segment length. The advantage of the proposal is that when a node-link fails or a routing node moves out it does not discard the entire path, only the segment has to discover a new path to reach segment end. This provides a clear energy saving and low overhead performance. Based on functionality it

routes the data packets in energy efficient route as described in Alogorithm-1 below.

Algorithm-1: EER-RS Based Routing Algorithm

Inputs:

$W(n) \rightarrow$ number of segments for nodes n .
 $d_s \rightarrow$ segment end node.

//-- Before forwarding the packets

A source node S forwards a request packet

for each node $n \neq d_s$ that have received Request packet **do**

 Compute remaining energy $B_n(t)$;

$B_n(t) = B_n - (B_{Tx} + B_{Rx} + B_{Idle})$;

$B_n = B_n(t)$;

 Node n send a reply packet with B_n ;

for end;

//-- On receiving Reply packets

for each segment path p_i **do**

for each node n to destination node d_s **do**

 Compute energy efficient path, $E(p_i)$,

$E(p_i) = \sum B_n$;

for end;

for end;

Select the path having maximum $E(p_i)$;

SECURITY ATTACKS IN MOBILE AD-HOC NETWORK :

MANET's has lots of security problems. Links are open and actively movable here thus bad-natured intruder can easily intrusion this network. Attacks matching to specific layer are displayed in table 1. The particular attacks are usually of two types i.e. internal and external attacks [4].

Attacks Matching to MANET Layers

LAYERS	ATTACKS
Transport Layer	Hijacking
Physical Layer	Eavesdropping, Jamming, Interference
Network Layer	Black Hole, Worm Hole, Spoofing, Sink Hole, Sybil
Application Layer	Code Attacks, Viruses
Data Link Layer	Denial-of-Service, Malicious Behaviour of Nodes

Internal Attacks

- ✓ Timing Attack
- ✓ Modification Attack
- ✓ Dropping Attack
- ✓ Fabrication Attack

External Attacks

Active Attacks: -It harms or alters the computer resources and involves modification of the information stream.

- ✓ Denial of Service Attack
- ✓ Spoofing
- ✓ Man-in-the-Middle
- ✓ ARP poisoning
- ✓ Ping Flood
- ✓ Smurf Attack
- ✓ Buffer Overflow
- ✓ Heap Overflow
- ✓ Formatting String Attack

Passive Attacks: -This type of attacks does not affect the system resource; they only observe or monitor the communication. The aim of this type of attack is to obtain information that is being transmitted [5]. These can be following

- ✓ Wiretapping
- ✓ Port Scan
- ✓ Idle Scan

Layer Attacks

- ✓ Gray Hole Attack
- ✓ Byzantine Attack
- ✓ Rushing Attack
- ✓ Partitioning Attack
- ✓ Black Hole Attack Worm Hole Attack
- ✓ Link Withholding Attack
- ✓ Sybil Attack
- ✓ Location Disclosure Attack
- ✓ Replay Attack
- ✓ Spoofing Attack

SOLUTIONS FOR SECURING MANET ROUTING PROTOCOLS :

To secure routing protocols from attacks lots of solutions are proposed by researchers like AODV, DSDV, DSR, OLSR and FSR etc. As routing is a significant task for Ad-hoc network, thus this should be more secure as viable. A protocol might be enough to please security problems and working terms. Below are few solutions .

- ✓ SAR (Security Aware Ad-hoc Routing)
- ✓ SAODV (Secure Ad-hoc on Demand Distance Vector)
- ✓ ARAN (Authenticated Routing for Ad-hoc Network)
- ✓ ARIADNE
- ✓ SRP (Secure Routing Protocol)
- ✓ SEAD (Secure Efficient Ad-hoc Distance Vector)
- ✓ SLSP (Secure Link State Routing Protocol)
- ✓ DSDV (Destination-Sequenced Distance Vector Protocol)
- ✓ DSR (Dynamic Secure Routing)

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