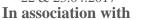


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Enhancement of Hybrid Power Scheme Based on Genetic Algorithm Using Three DC Source

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ABSTRACT

Now a day's Solar Power is essential for all domestic purposes due to the demand of power consumption. But the single Solar system doesn't give the consistent yield due to sun power illumination. To conquer this issue, this project work presents enhancement of hybrid power scheme utilizes with PV/Fuel cell/Battery power to produce constant power using genetic algorithm (GA). The proposed hybrid scheme initially utilizes four module power controllers for independently expose to different duty cycles. The constant DC source is carried out by hybrid power scheme is to optimize the different duty cycle and to provide constant voltage through the load. This paper presents Genetic algorithm (GA) based model to enhance the duty cycle of the controller for a hybrid power control scheme. The simulation result was carried out by MATLAB/SIMULINK. From the model, the data required are generated and the performance is analyzed using a genetic algorithm. The GA based approach indicates better performance when compared with neural network controller.

Keywords: Hybrid DC source, Genetic algorithm, Duty cycle Enhancement.

I. INTRODUCTION

This document is a template. The standard fossil fuel vitality such as petroleum, natural gas, and coal are takes care of power demand in this day and age. The renewable vitality sources (solar, the wind, tidal, geothermal, etc.,) have more attention as an alternative vitality. In this paper, the photovoltaic (PV) vitality appears stopped to attract for electricity generation. Since, solar power grid generation relies on the sun illumination stage, encompassing temperature and eccentric darkness of PV [1, 2].

Fuel cell (FC) [2, 3, 4] exhibited to design the promising of extra power source that are advantages of neatness, more effectiveness, and prominent unwavering quality. For the most part, FC is perform extended turn on process and is carried out minimum time-consuming process of dynamic response to bungle power between the loads.

Batteries are for the most part taken a capacity component for charging and discharging power to improving the transitions of dynamic characteristics. Consecutively, the three power scheme initialized by the DC source of PV/FC/Battery [5], which is known as hybrid power scheme. When evaluation individual sourced system as well as hybrid power scheme has to certainly offer by more quality output reliable and more efficiency. In this system consists of a storage feature, with utilize the power exist of bi-direction voltage flow. These three information control sources produce a decent capacity to supply voltage to the load alone.

Many hybrid power systems cannot able to maintain the constant output voltages for various power electronic converter application up to now. The ordinary techniques are used for individual power scheme provide smallest amount of voltage to overcome the problem evaluate with hybrid power scheme [6]. Nevertheless, the most traditional power scheme topology is very complex communicate system. Because, the performance time should be high together with large

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amount of devices utilize the process provides high power losses. Here, quite a few stage of power conversion are utilizes the hybrid power scheme, which are changed by a three input converter. Thus, the result of process is consolidated through various power sources in individual structure. To defeat the problem suggested the boost converters having additional advantages of multi-objective optimization approach for hybrid power scheme by changing the duct cycle values randomized for developing the constant power deliver to the load. This paper deals with the multi-input dc-dc boost converter maintain the constant output voltage, to optimize the hybrid power system and fast output response using a genetic algorithm (GA).

Three input cuck regulated model fuzzy logic design [7] to interfacing the wind energy sources produce the electrical energy in to the system. This type of fuzzy the logic controller can be deliver yield streams relating to each power station and their reference voltage. DC-DC converter for battery [8] presents a controller is proficient to operating in bidirectional and to regulate the constant output voltage under different inputs values. The MPPT control algorithm present [9] that includes automatic determination and to permits the conventional converter of optimal operation control circuit under steady state environment with different duty cycles. DC-DC boost converters [10] present a design of integrated photovoltaic by applying back propagation artificial algorithm was produced boosted output voltage and sudden changes for solar illumination levels.

Modeling and design of regulated power supply approaches proposed [11] system conveying output source for converter topology with using a genetic algorithm (GA). This output impacts of parameters such like that increasing population size, iteration value, and varying the probability of mutation and probability of crossover also presented using MATLAB/SIMULINK.

Optimization of boost converter power loss was presented [12] a design of converter switching operation can be controlled, voltage swells by using an optimization technique. Utilizing these techniques easily obtained constant boosted output voltage by MATLAB. Hybrid power scheme optimization model were proposed for the design of [13] solar and wind energy system. This power scheme comprises of solar cells, wind turbines, and storage batteries are optimized using

objective function. This function optimized the total cost, initial cost, and yearly replacement cost can be maintained in the proposed converter.

Three input dc-dc converter was presented [14] fuel cells and battery packs are used to compensate for the immediate power changes in the microgrid that problem exhibits to the un even power loss of solar cells are required to the microgrid, and resultant of that power lose occurs sudden intrusion of the main grid. To overcome this losses using enhancement technique for three input dc source provide low level settling time and rise time in their grid connected system.

Optimization of hybrid energy system presented [15] an endeavour to convey the concept of the hybrid renewable energy system (HRES) and the condition of different values can be used to improve the simulink results. The enhancement techniques are used to reduce the swells and produce high output voltage for the microgrid application. Enhancement methods are utilized to reduce the investment cost and reliable resource.

II. DIFFERENT MODES OF OPERATION

The circuit comprise of a four MOSFET performs effectiveness of controlled with the independently depends on four duty ratios such as d_1 d_2 d3and d_4 . Fig .1 performs with boost converter diodes D_1 and D_2 lead correlative way with comparing switches S_1 and S_2 .

Referring this circuit when the switches S_3 and S_4 are get started with great operating mode and then possible of corresponding diodes D_3 and D_4 are biased followed by the complex criteria of battery voltage. These two switches turn-OFF state, the diodes D_3 and D_4 , ready to lead conduct the input currents iL_1 , iL_2

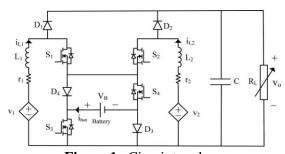


Figure 1. Circuit topology

In this circuit is hybrid power system applications and continuous current mode (CCM) is conceivable. It has the converter topology is seen from the solar or Fuel cell systems, an major problem is to reach an sufficient current swell and kept up the consistent yield voltage. The continuous current swells as well as input power are limited to make a correct power adjust along with the input powers simultaneously carried out the load. Consequently, the proposed hybrid scheme converter has been acquired the relentless state yield and quick yield reaction of the converter.

For the usually utilized condition occur of the storage element are considered by the DC modules with operation performs three modes, which are characterized to the proposed hybrid power scheme converters. These distinctive operation conditions are satisfied with d_3 , d_4 <minimization (d_1 , d_2) duty cycle ratios . While exceeding the process of duty ratio does not a failure in this converter. To defeat this issues always consider as the duty cycle ratio d_1 is smaller than duty cycle ratio d_2 , then only switches are operated as autonomously.

A. Mode1:

In the mode 1, v_1 and v_2 charged power sources are providing through the load and without battery storage. That is fundamental modes are done in this mode to control the yield voltage. As unmistakably observed from the basic circuit topology, there are two approach to direct control of input power sources streams iL_1 , iL_2 . Without experiencing the battery;

- \bullet Current flow direction 1: S_4 – D_3
- \bullet Current flow direction 2: S_3-D_4 .

The working principal of mode 1 is feasible for applying the primary way. According this position switch S_4 is OFF and diode D_3 also OFF condition. The exchanging states are portrayed in Fig 2-4.

1) Condition state 1 ($0 < t < d_1T$)

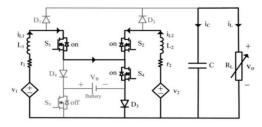


Figure 2. Condition State $1(0 < t < d_1T)$

In the main operation mode, at t=0 the state of Switches S_1 and S_2 are turned ON until the inductors L_1 and L_2 are charged over the voltages v_1 and v_2 separately.

2) Condition state 2 $(d_1T < t < d_2T)$

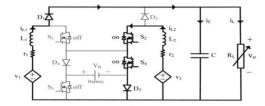


Figure 3. Condition State 2 ($d_1 T < t < d_2 T$)

In stage 2, the operation technique of $t = d_1T$ are finished by Switch S_1 will to low state and this time switch S_2 is continuously ON position (if d_1 is smaller than d_2), the inductor L_1 is released to the charged voltage v_1 – v_0 , and output voltage is conveyed to the load. This circumstance inductor L_2 gets charged across the source v_2 .

3) Condition state 3 $(d_2T < t < T)$

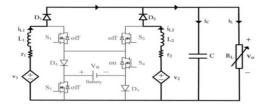


Figure 4. Condition State 3 $(d_2T < t < T)$

In stage 3, procedure of $t=d_2T$ condition applicable of switch S_2 will be proceeds for quite little provided the voltage. While, the inductor L_2 is clearly decompose the voltage level beyond the v_2 – v_0 voltage as similar to the inductor L_1 . This operation is satisfied by the conventional theory as followed the voltage and current the associated by the condition are acquired with output response v_0 .

$$v_0 = \frac{v_1 - r_1 * i_{L1}}{1 - d_1} \tag{1}$$

$$v_0 = \frac{v_2 - r_2 * i_{L2}}{1 - d_2} \tag{2}$$

$$C: (1-d_1)Ti_{L1} + (1-d_2)Ti_{L2} = T \frac{v_0}{R_L}$$
(3)

This operation mode is utilized to deal with the individual power sources deliver the input module goes on a kind of perspective power obtained by the duty cycle values and the next power source is used to 2) Condition state 2 $(d_4T < t < d_1T)$ coordinate the output voltage.

B. Mode 2:

In the second mode, voltage source v_1 and v_2 along with the battery discharging state is incorporated for providing through the load. The basic converter circuit (Fig 1), the MOSFET switches S_3 and S_4 are turned ON. This procedure releasing is happened at whatever point the stream of current is between the i_{L1} and i_{L2} .

In any case, the discharging of the battery can just a single of the switches S_1 or S_2 is kept in ON position. This mode can be gotten by the resultant of maximum power. At this time duty cycle ratio diodes d₁and d₂, the corresponding inductors current flow through the iL_1 , iL_2 .

Duty ratio d₄ as followed by the condition should be control the discharging power module of battery, which is concerning the certainties process continuously with occurs the mode switch S₄ operates with quite high condition. Then, it comes about passing through the currents iL_1 , iL_2 provides for input belongs to the battery. As delineated in Fig 5-8, there are four attractive processes are operates by the DC converter module, as its individual exchanging state.

Condition state 1 ($0 < t < d_4T$)

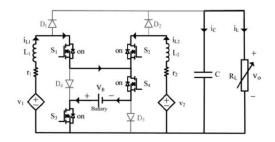


Figure 5. Condition State 1 $(0 < T < d_4T)$

In stage1 t=0 switches S_1 , S_2 , and S_4 are absolutely greater than the other switches that instantaneously process of inductors L₁ and L₂ are existing improve the level across the voltages $v_1 + v_B$ and $v_2 + v_B$. These charged voltages are given to the load and create the steady output voltage for this switching state 1. Which state works according to the duty cycle ratio (supposition $d_1 < d_2$) used to turn ON the comparing switches.

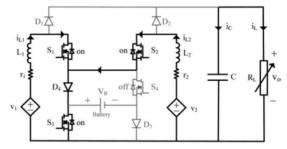


Figure 6. Condition State 2 $(d_4T < t < d_1T)$

In stage2 $t = d_4T$ at this issues time switch S_4 is killed, while the switches S_1 and S_2 are quite with the higher than the others, which condition provides for inductors L_1 and L_2 are obtained with increase the voltage level across the v_1 and v_2 respectively.

Condition state 3 ($d_1T < t < d_2T$)

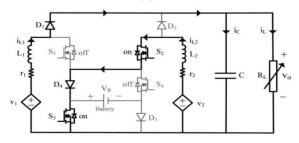


Figure 7. Condition State 3 $(d_1T < t < d_2T)$

In stage 3 $t = d_1T$ at this condition switch, S_t is execute with under low condition the meantime of inductor L_1 is simultaneously degrades the voltage beyond $v_1 - v_0$ at this stage L_2 , is quite accused of voltages across v_2 .

Condition state 4 $(d_2T < t < T)$

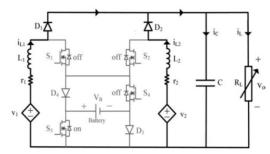


Figure 8. Condition State 4 $(d_2T < t < T)$

In stage 4 t = d_2T , this condition switch S_2 is likewise higher than the other switches, until the inductors L₁ and L₂ are simultaneously degrades the process over the voltage v_1 – v_0 and v_2 – v_0 individually. This operation is satisfied by the conventional theory as followed the voltage and current the associated by the condition are 1) Condition state 1 ($0 < t < d_3T$) acquired with output response v_0 .

$$v_0 = \frac{v_1 - r_1 * i_{L1} + d_4 v_B}{1 - d_1} \tag{4}$$

$$v_o = \frac{v_2 - r_2 i_{L2} + d_4 v_B}{1 - d_2} \tag{5}$$

$$C: (1 - d_1)Ti_{L1} + (1 - d_2)Ti_{L2} = T\frac{v_o}{R_L}$$
 (6)

In mode 2 is carried out by the v_1 and v_2 input power sources are referred to get the resultant of the duty ratios d₁, d₂ and the battery degrades as well as the power utilized balance output voltage by the limited duty cycle ratio d₄.

C. Mode 3:

In mode 3 provide for one or more different input source of v₁and fuel cell v₂are greatly extension of voltage as well as providing through the load and battery charging execution are incorporated into this mode.

As observed from the converter circuit, when the switches S₃and S₄are goes excessively turned OFF at these time switches S_1 and S_2 are quite higher than the others switches, then the inductor i_{L1} and i_{L2} provides the currents simultaneously followed by the access of diode D₄, battery and diode D₃. According to the condition battery is concurrently attended. The charging power is underneath the P_{max} esteem charging, to change the condition state of a one set of the switches S₃,S₄ earlier than the switches S1, S2 goes to high state.

According to the condition state of this operation mode, when the switch S₃ is turned ON right now battery is holding off on charging until the switch goes too turned OFF state. These conditions state are illustrated in Fig 9-12.

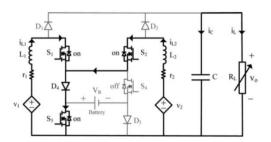


Figure 9. Condition State 1 $(0 < t < d_3T)$

At this arrangement 1 t = 0 conditions that happens with the MOSFET S₁, S₂ and S₃ are greatly higher state compare to other states as shown fig.9.simultaneously the inductors L_1 and L_2 are accused by the v_1 and v_2 , correspondingly.

2) Condition state 2 $(d_3T < t < d_1T)$

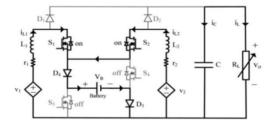


Figure 10. Condition State 2 ($d_3T < t <$

 d_1T)

In stage 2, $t = d_3T$, this condition is fulfilled by low state of the switch S_3 and the MOSFET switches S_1 , S_2 are at a standstill greater condition, and the inductors L₁ and L₂ to get charged through make use of the v₁- v_B and v₂- v_B, separately.

3) Condition state 3 $(d_1T < t < d_2T)$

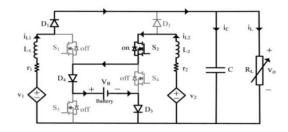


Figure 11. Condition State 3 $(d_1T < t < d_2T)$

In stage 3, $t = d_1T$ condition takes after the switch S_1 is goes to low condition and the inductor L₁is degrade across the voltage v₁- v₀, at the similar time inductor L₂ is as yet charging across the voltage v₂- v_B. This operation is satisfied by the conventional theory as followed the voltage and current the associated by the condition are acquired with output response v_0

$$v_0 = \frac{v_1 - r_1 i_{L1} - (d_1 - d_3) v_B}{1 - d_1}$$
 (7)

$$v_0 = \frac{v_2 - r_2 i_{L2} - (d_2 - d_3) v_B}{1 - d_2} \tag{8}$$

$$C: (1 - d_1)Ti_{L1} + (1 - d_2)Ti_{L2} = T\frac{v_o}{R_L}$$
(9)

4) Condition state 4 $(d_2T < t < T)$

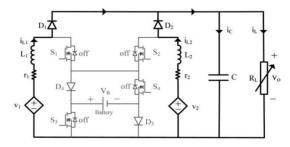


Figure 12. Condition State 4 $(d_2T < t < T)$

In arrangement 4, $t=d_2T$ condition is satisfied by the condition of low state switch S_2 and the inductor L_2 , L_1 is released make use of the voltage v_2 – v_0 .

III.PROPOSED METHODOLOGY

Genetic algorithms are the most specified analysis ideal approaches to solve a complex optimization problem. This approach can be extremely broad calculation and can function admirably in any pursuit space. The genetic algorithm is proficient to produce an exact the expert solution. This algorithm also produces several solutions to a given problem.GA is standout amongst the powerful methods with which to quick response to create an exact the expert solution for a specified problem. GA consists of the three frame work followed by the exact solution of essential population to arrange the many random values to evolve condition such as selection rules, crossover and mutation process as well as providing the better solution of the fitness function. This problem solve the required fitness function is minimizing the maximum rise time and settling time.

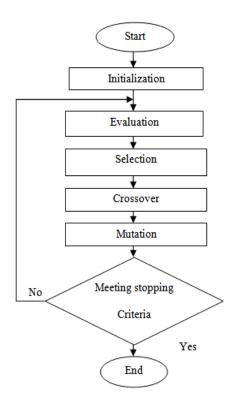


Figure 13. Flow chart of the genetic algorithm.

GA procedure based on the flowchart of fig 13.intially the GA select the parameters randomly for population size at initial stage and then produce the children from parents. This parent produces the children for next generation by using genetic algorithm flow chart.

IV. RESULTS AND DISCUSSION

In this paper, GA is used to optimize the duty cycle ratio in order to minimize the rise time and settling time. The boost converter duty cycle ratios are optimized by using MATLAB/Simulink. The optimized duty cycle values are obtained by using the objective function. Now the population size is 100, initial population size is 1and iteration value is 10. After the iteration can able to satisfy the minimum rise and settling time to produce the constant output voltage for proposed converter. Generally, the dc-dc boost converter duty cycle objective function as follows:

$$D = \sum_{n=0}^{Ts} \frac{Von}{T}$$
 (10)

Where *Ts* is the Rise time,

Von is the pulse on time and T is the total time period

T = Ton + Toff . This duty cycle ratio values can be obtained by MATLAB/Simulation result. After the simulation duty cycle values are saved in workspace file. Whenever applying the gate pulse to the proposed converter and take saved duty cycle ratio values are consider. The best optimal solution is obtained by changing the population size. Optimization results after 10 iteration as follows as:

Parameter	Values
Number of	100
population size	
Crossover	1.0
Probability	
Mutation probability	0.00001
Fitness value	0.006

Table 1. Parameters used in GA

This table 1.shows the parameter used in GA in order to optimize the duty cycle ratio. By selecting the population size as 100, the crossover probability as 1.0, mutation probability as 0.00001 and the fitness value as 0.006. The simulation block of GA used for duty cycle optimization using MATLAB is shown in fig 14.

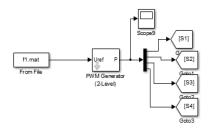


Figure 14. Duty cycle optimization using MATLAB.

Fig14.optimized values are given to the pulse generator and produce the duty cycle waveform for corresponding converter circuit in order to optimize duty cycle ratio.

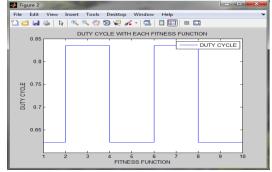


Figure 15. Duty cycle optimization Simulation

The duty cycle is optimize in the range of 0.85 is shown in Fig 15 with the given fitness values of 0.006 the duty cycle is optimized and by changing the fitness values of duty cycle can also be varied. This boosted output voltage waveform produces only after the 10th iteration and corresponding duty cycle ratio is used in this converter with the given values, the duty cycle is optimize as 0.85 and the corresponding boost output voltage using GA is shown in Fig 16.

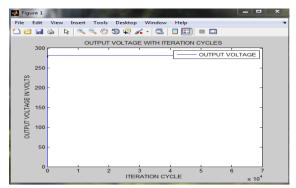


Figure 16. Boost output voltage using GA

V. COMPARISION OF ANN AND GA SIMULATION RESULTS

The GA model provides for duty cycle optimization of DC-DC boost converter from hybrid power scheme. The rise time required is 0.0005sec and settling time 0.009sec. For performance comparison ANN model was developed the rise time 0.005sec and its settling time 0.01sec. On comparing the performance of GA model with ANN model, the GA model shows better performance when compared with ANN model. Fig 17 is obtained the constant voltage level proceeding with proposed method under different operation mode for a hybrid power system using GA and also obtained better performance of settling time (Ts) and rise time (Tr), which this condition to maintain the continuously constant power delivered to the load.

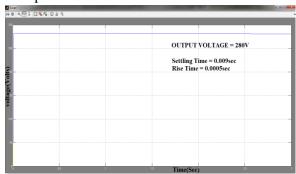


Figure 17. Boost output voltages using MATLAB/Simulink

The same problems were solved by the artificial neural network controller to obtained less settling, rise time and could not able to control the hybrid power scheme. But compare the genetic algorithm (GA) results is able to control the system and also obtained better optimization performance are given table 2.

Parameters	ANN	GA
Output	273.5V	280V
Voltage		
Tr	0.005sec	0.0005 sec
Ts	0.01 sec	0.009 sec

Table 2. Comparison between ANN and GA

VI.CONCLUSION

A hybrid power scheme of dc-dc boost converter structure was designed and better performance was obtained using GA. This hybrid power scheme can be apply for a solar (PV), FC, battery storage system and enhancement duty cycle ratios values are applied to the proposed converter circuit. This converter produces the yield output voltage source is obtained by using the Genetic algorithm.

This converter produces 280V helped voltage and fast output response is 0.009sec settling time and 0.0005sec rise time results are obtained by using a genetic algorithm (GA).

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