

A Study on Conservative Pseudo Quasi-Conformal Curvature Tensor in K-Contact Manifold

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ABSTRACT

The paper deals with the study on Pseudo quasi-conformal curvature tensor in K-contact manifolds and it is shown that the manifold is Einstein.

Keywords : Conservative, Conformal Curvature Tensor, Einstein, K-Contact Manifold.

1. INTRODUCTION

Geometry of contact metric manifolds is important because of their applications, for instance in the theory of Einstein metrics K-contact manifolds have nice topological properties. Two important classes of contact manifolds are K-contact manifolds and Sasakian manifolds ([3], [4], [12]). K-contact and Sasakian manifolds have been studied by several authors such as ([1], [7], [9], [10]). It is known that if the characteristic vector field of a contact metric manifold is Killing vector field then the manifold is called a K-contact manifold. It is well known that every Sasakian manifold is K-contact, but the converse is not true, in general. However a three-dimensional K-contact manifold is Sasakian.

In [14], Yano and Sawaki defined and studied a tensor field W called quasi-conformal curvature tensor on a Riemannian manifold which includes both the conformal curvature tensor and concircular curvature tensor as special cases. In [13], A.A. Shaikh and Sanjib Kumar Jana introduced and studied the pseudo quasi-conformal curvature tensor and it is a generalization of conformal, quasi-conformal [1], concircular and projective curvature tensor as special cases. Recently, D.G. Prakasha et.al [8] and Satyabrota Kundu [11] studied different properties of pseudo quasi-conformal curvature tensor in P-Sasakian manifolds.

Motivated by the above work in this research article we studied pseudo quasi-conformal curvature tensor in K-contact manifolds:

The paper is organized as follows: Section 2 deals with preliminaries of K-contact manifold. Section 3 deals with the study pseudo quasi-conformally conservative K-contact manifold.

2. PRELIMINARIES

An n -dimensional differentiable manifold M is said to have an almost contact structure (ϕ, ξ, η) if it carries a tensor field ϕ of type $(1,1)$, a vector field ξ and a 1-form η on M satisfying

$$(2.1) \quad \phi^2 X = -X + \eta(X)\xi, \quad \phi\xi = 0, \quad \eta(\xi) = 1, \quad \eta \cdot \phi = 0.$$

If g is a Riemannian metric with almost contact structure that is,

$$(2.2) \quad g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \quad \eta(X) = g(X, \xi).$$

Then M is called an almost contact metric manifold equipped with an almost contact metric structure (ϕ, ξ, η, g) and denoted by (M, ϕ, ξ, η, g) .

If on (M, ϕ, ξ, η, g) the exterior derivative of 1-form η satisfies,

$$d\eta(X, Y) = g(X, \phi Y).$$

Then (M, ϕ, ξ, η, g) is said to be a contact metric manifold.

If moreover ξ is Killing vector field, then M is called a K-contact manifold. A K-contact manifold is called Sasakian, if the relation

$$(2.3) \quad (\nabla_X \phi)Y = g(X, Y)\xi - \eta(Y)X,$$

holds, where ∇ denotes the covariant differentiation with respect to g . From (2.3), we get

$$(2.4) \quad \nabla_X \xi = -\phi X, \quad (\nabla_X \eta)Y = g(X, \phi Y).$$

In a K-contact manifold M the following relations holds:

$$(2.5) \quad g(R(\xi, X)Y, \xi) = g(X, Y) - \eta(X)\eta(Y),$$

$$(2.6) \quad R(X, Y)\xi = \eta(Y)X - \eta(X)Y,$$

$$(2.7) \quad R(\xi, X)\xi = \eta(X)\xi - X,$$

$$(2.8) \quad S(X, \xi) = (n-1)\eta(X),$$

for any vector fields X, Y . Where R is the Riemannian curvature tensor and S is the Ricci tensor of the manifold M .

The pseudo quasi-conformal curvature tensor [13] \tilde{W} of type $(1, 3)$ on a K-contact manifold is defined by

$$(2.9) \quad \tilde{W}(X, Y)Z = (p+d)R(X, Y)Z + \left[q - \frac{d}{n-1} \right] [S(Y, Z)X - S(X, Z)Y] \\ + q[g(Y, Z)QX - g(X, Z)QY] - \frac{r(p+2(n-1)q)}{n(n-1)} [g(Y, Z)X - g(X, Z)Y],$$

for all vector fields X, Y, Z , where p, q, d are arbitrary constants not simultaneously zero, R is the Riemannian curvature tensor, S is the Ricci tensor, Q is the Ricci operator and r is the scalar curvature tensor of the manifold M .

In particular, if

- $p = q = 0, d = 1$ in (2.9) then \tilde{W} reduces to the projective curvature tensor.
- $p \neq 0, q \neq 0, d = 0$ in (2.9) then \tilde{W} reduces to the quasi-conformal curvature tensor.
- $p = 1, q = -\frac{1}{n-2}, d = 0$ in (2.9) then \tilde{W} reduces to the conformal curvature tensor.
- $p = 1, d = q = 0$ in (2.9) then \tilde{W} reduces to the concircular curvature tensor.

3. PSEUDO QUASI-CONFORMALLY CONSERVATIVE K-CONTACT MANIFOLD

In this section, we study the conservative Pseudo Quasi-Conformal curvature tensor in K-contact manifold.

Then we have

$$(3.1) \quad \text{div } \tilde{W}(U, V)Z = 0.$$

Differentiating (2.9) covariantly along the vector field U_i , we get

$$(3.2) \quad (\nabla_{U_i} \tilde{W})(U, V)Z = (p + d)(\nabla_{U_i} R)(U, V)Z + \left[q - \frac{d}{(n-1)} \right] [(\nabla_{U_i} S)(V, Z)U - (\nabla_{U_i} S)(U, Z)V] \\ + q[g(V, Z)(\nabla_{U_i} Q)U - g(U, Z)(\nabla_{U_i} Q)V] - \frac{dr(U_i)}{n(n-1)} [p + 2(n-1)q][g(V, Z)U - g(U, Z)V].$$

On contracting (3.2), we obtain

$$(3.3) \quad \text{div } \tilde{W}(U, V)Z = (p + d) \text{div } R(U, V)Z + \left[q - \frac{d}{(n-1)} \right] [(\nabla_U S)(V, Z) - (\nabla_V S)(U, Z)] \\ - \left[\frac{p}{n(n-1)} - \frac{(n-4)q}{2n} \right] [g(V, Z)dr(U) - g(U, Z)dr(V)].$$

With the help of (3.1) in (3.3), we have

$$(3.4) \quad \left[p + q + \frac{d(n-2)}{(n-1)} \right] [(\nabla_U S)(V, Z) - (\nabla_V S)(U, Z)] \\ - \left[\frac{p}{n(n-1)} - \frac{(n-4)q}{2n} \right] [g(V, Z)dr(U) - g(U, Z)dr(V)] = 0.$$

By substituting $U = \xi$ in (3.4), we get

$$(3.5) \quad \left[p + q + \frac{d(n-2)}{(n-1)} \right] [(\nabla_\xi S)(V, Z) - (\nabla_V S)(\xi, Z)] \\ - \left[\frac{p}{n(n-1)} - \frac{(n-4)q}{2n} \right] [g(V, Z)dr(\xi) - g(\xi, Z)dr(V)] = 0.$$

We know that

$$(3.6) \quad (\nabla_V S)(\xi, Z) = VS(\xi, Z) - S(\nabla_V \xi, Z) - S(\xi, \nabla_V Z) \\ = S(\phi V, Z) - (n-1)g(\phi V, Z).$$

And

$$(3.7) \quad (\nabla_V S)(\xi, Z) = 0.$$

By using (3.6), (3.7) and $dr(\xi) = 0$ in (3.5), we get

$$(3.8) \quad \left[p + q - \frac{d(n-2)}{(n-1)} \right] [S(\phi V, Z) - (n-1)g(\phi V, Z)] = \left[\frac{p}{n(n-1)} - \frac{(n-4)q}{2n} \right] \eta(Z)dr(V).$$

Replacing $Z = \phi Z$ in (3.8), we obtain

$$(3.9) \quad S(\phi V, \phi Z) = (n-1)g(\phi V, \phi Z),$$

provided $\left[p + q + \frac{d(n-2)}{(n-1)} \right] \neq 0$. On simplifying (3.9), we get

$$(3.10) \quad S(V, Z) = (n - 1)g(V, Z),$$

On contracting (3.10), we have

$$(3.11) \quad r = n(n - 1).$$

Hence, we state the following:

Theorem 3.1. If in a K-contact manifold the Pseudo quasi-conformal curvature tensor is conservative, then the manifold is Einstein and scalar curvature $r = n(n - 1)$.

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