

## Some Results on Generalized Recurrent K-Contact Manifolds Admitting Quarter-Symmetric Metric Connection

S.N. Manjunath<sup>a</sup>\*

<sup>a</sup>\*Lecturer, Department of Science, Govt. VISSJ Polytechnic, Bhadravathi, Karnataka, India \* Corresponding author. E-mail : mathsmanju@gmail.com

### ABSTRACT

### Article Info

Volume 9, Issue 1	The objective of the present paper is to study some properties of generalized $\phi$ -
Page Number : 558-565	recurrent K-contact manifold admitting quarter-symmetric metric connection.
Publication Issue	
January-February-2022	Keywords: K-Contact Manifold, Generalized Recurrent.
Article History	
Accepted : 01 Jan 2022	AMS Subject Classification (2010) : 53C05, 53D10, 53C20, 53C15, 53C25
Published : 20 Feb 2022	

### 1. Introduction:

In 1924, A. Friedman and J.A. Schouten [4] introduced the notion of a semi-symmetric linear connection on a differentiable manifold. In 1932, H.A. Hayden [8] introduced the idea of metric connection with torsion on a Riemannian manifold. In 1970, K. Yano [16] studied some curvature and conditions for semi-symmetric connections in Riemannian manifolds. In 1975, S. Golab [5] defined and studied quarter-symmetric linear connection on а differentiable manifold.

The notion of local symmetry of a Riemannian manifold has been weakened by many authors in several ways to a different extent. As a weaker version of local symmetry, Takahashi [15] introduced the notion of local  $\phi$ -symmetry on a Sasakian manifold. Generalizing the notion of  $\phi$ -symmetry, the authors De et al. [3] introduced the notion of  $\phi$ -recurrent

Sasakian manifolds. This notion was further studied by many authors like C.S. Bagewadi and et al. ([1], [6], [7]), Nagaraja [10], A.A. Shaikh and Ananta Patra [14]. In the present paper we studied generalized  $\phi$  recurrent K-contact manifold admitting quartersymmetric metric connection. The second section devoted to the basic concepts of K-contact manifold. In the third section we study the relation between the Levi-Civita connection and the quarter-symmetric metric connection in a K-contact manifold. In the fourth section we study the generalized recurrent Kcontact manifold with respect to the quartersymmetric metric connection. In the next section we study the generalized  $\phi$ -recurrent K-contact manifold with respect to the quarter-symmetric metric connection. In the section we studied C-Bochner generalized  $\phi$ -recurrent K-contact manifold with respect to the quarter-symmetric metric connection

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A linear connection  $\widetilde{\nabla}$  in an *n*-dimensional differentiable manifold is said to be a quarter-symmetric connection if its torsion tensor *T* is of the form

(1.1) 
$$T(X,Y) = \widetilde{\nabla}_X Y - \widetilde{\nabla}_Y X - [X,Y]$$
$$= \pi(Y)F X - \pi(X)F Y,$$

where  $\pi$  is a 1-form and F is a tensor of type (1,1) and quarter-symmetric linear connection  $\widetilde{\nabla}$  satisfies the condition

$$\left(\widetilde{\nabla}_X g\right)(Y,Z) = 0$$

for all  $X, Y, Z \in \mathcal{X}(M)$ , where  $\mathcal{X}(M)$  is the Lie algebra of vector fields of the manifold M, then  $\widetilde{\nabla}$  is said to be a quarter-symmetric metric connection.

For contact manifold admitting quarter-symmetric connection we take  $\pi = \eta$  and  $F = \phi$  in (1.1) then the equation can be written as

(1.2) 
$$T(X,Y) = \eta(Y)\phi X - \eta(X)\phi Y.$$

### 2. Preliminaries:

An *n*-dimensional differentiable manifold *M* is said to have an almost contact structure ( $\phi$ ,  $\xi$ ,  $\eta$ ) if it carries a tensor field  $\phi$  of type (1,1), a vector field  $\xi$  and a 1-form  $\eta$  on *M* respectively such that,

(2.1) 
$$\phi^2 X = -X + \eta(X)\xi, \ \phi\xi = 0, \ \eta(\xi) = 1, \ \eta \cdot \phi = 0.$$

Thus a manifold *M* equipped with this structure is called an almost contact manifold and is denoted by  $(M, \phi, \xi, \eta)$ . If *g* is a Riemannian metric on an almost contact manifold *M* such that,

(2.2)  $g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \qquad \eta(X) = g(X, \xi),$ 

(2.3) 
$$g(X,\phi Y) = -g(\phi X,Y),$$

where *X*, *Y* are vector fields defined on *M*, then *M* is said to have an almost contact metric structure ( $\phi$ ,  $\xi$ ,  $\eta$ , g) and *M* with this structure is called an almost contact metric manifold and is denoted by (M,  $\phi$ ,  $\xi$ ,  $\eta$ , g).

If on  $(M, \phi, \xi, \eta, g)$  the exterior derivative of 1-form  $\eta$  satisfies,

$$d\eta(X,Y) = g(X,\phi Y)$$

then  $(M, \phi, \xi, \eta, g)$  is said to be a contact metric structure and M equipped with a contact metric structure is called contact metric manifold.

If  $\xi$  is a killing vector field, then M is called a K-contact Riemannian manifold. A K-contact Riemannian manifold is called Sasakian, if the relation

### (2.4) $(\nabla_X \phi)Y = g(X, Y)\xi - \eta(Y)X$

holds, where  $\nabla$  denotes the operator of covariant differentiation with respect to g.



In a K-contact manifold *M*, the following relations holds:

(2.5) 
$$\nabla_X \xi = -\phi X,$$
  
(2.7)  $g(R(X,Y)Z,\xi) = g(Y,Z)\eta(X) - g(X,Z)\eta(Y),$   
(2.8)  $R(\xi,X)\xi = -X + \eta(X)\xi,$ 

(2.8) 
$$S(X,\xi) = (n-1)\eta(X),$$

where R and S are the Riemannian curvature tensor and the Ricci tensor of M, respectively.

**Definition 2.1:** A K-contact manifold is called generalized  $\phi$ -recurrent if its curvature tensor *R* satisfies the condition

(2.9) 
$$\phi^{2}((\nabla_{W} R)(X,Y)Z) = \alpha(W)R(X,Y)Z + \beta(W)\{g(Y,Z)X - g(X,Z)Y\}$$

for arbitrary vector fields *X*, *Y*, *Z* and *W*. Where \$R\$ is the Riemannian curvature tensor,  $\alpha$  and  $\beta$  are two 1-forms defined by

(2.10) 
$$\alpha(W) = g(W, \rho_1), \ \beta(W) = g(W, \rho_2)$$

where  $\rho_1$  and  $\rho_2$  are vector fields associated with 1-forms  $\alpha$  and  $\beta$  respectively.

# 3. Relation between the curvature tensors of Levi-Civita connection and the quarter-symmetric metric connection in a K-Contact manifold:

A quarter-symmetric metric connection  $\widetilde{\nabla}$  in a K-Contact manifold is given by

(3.1) 
$$\widetilde{\nabla}_X Y = \nabla_X Y - \eta(X)\phi Y.$$

Therefore equation (3.1) is the relation between the Levi-Civita connection and the quarter-symmetric metric connection on a K-Contact manifold.

A relation between the curvature tensor of M with respect to the quarter-symmetric metric connection  $\widetilde{\nabla}$  and the Levi-Civita connection  $\nabla$  is given by

(3.2) 
$$\tilde{R}(X,Y)Z = R(X,Y)Z + 2g(\phi X,Y)\phi Z + [\eta(X)g(Y,Z) - \eta(Y)g(X,Z)]\xi + [\eta(Y)X - \eta(X)Y]\eta(Z)$$

where  $\tilde{R}$  and R are the Riemannian curvature of the connection  $\tilde{\nabla}$  and  $\nabla$ , respectively. From (3.2), it follows that

(3.3)  $\tilde{S}(Y,Z) = S(Y,Z) - g(Y,Z) + n \eta(Y)\eta(Z)$ 

where  $\tilde{S}$  and S are the Ricci tensors of the connection  $\tilde{\nabla}$  and  $\nabla$ , respectively. Contracting (3.3), we get

 $(3.4) \qquad \tilde{r} = r$ 

where  $\tilde{r}$  and r are the scalar curvatures of the connection  $\tilde{\nabla}$  and  $\nabla$ , respectively.

### 4. Generalized recurrent K-contact manifold with respect to the quarter-symmetric metric connection:

We define a generalized recurrent K-contact manifold with respect to the quarter-symmetric metric connection if its curvature tensor  $\tilde{R}$  satisfies the condition

(4.1)  $(\widetilde{\nabla}_W \widetilde{R})(U,V)Z = \alpha(W)\widetilde{R}(U,V)Z + \beta(W)\{g(V,Z)U - g(U,Z)V\}$ 

where  $\alpha$  and  $\beta$  are 1-form and it is defined by

(4.2) 
$$\alpha(W) = g(W, \rho_1), \ \beta(W) = g(W, \rho_2)$$

where  $\rho_1$  and  $\rho_2$  are vector fields associated with 1-forms  $\alpha$  and  $\beta$  respectively. Now by substituting the value of  $U = Z = \xi$  in (4.1) then we have

(4.3) 
$$(\widetilde{\nabla}_W \widetilde{R})(\xi, V)\xi = \alpha(W)\widetilde{R}(\xi, V)\xi + \beta(W)\{\eta(V)\xi - V\}$$

It is also known that

(4.4) 
$$(\widetilde{\nabla}_W \widetilde{R})(\xi, V)\xi = \widetilde{\nabla}_W \widetilde{R}(\xi, V)\xi - \widetilde{R}(\widetilde{\nabla}_W \xi, V)\xi - \widetilde{R}(\xi, \widetilde{\nabla}_W V)\xi - \widetilde{R}(\xi, V)\widetilde{\nabla}_W \xi$$

then by virtue of (3.2), (3.1) and (2.7) in (4.4) then the equation (4.4) reduces in the form

(4.5) 
$$(\widetilde{\nabla}_W \widetilde{R})(\xi, V)\xi = 0.$$

By substituting the above value of equation (4.5) in (4.3) then we have

(4.6) 
$$\alpha(W)\tilde{R}(\xi,V)\xi + \beta(W)\{\eta(V)\xi - V\} = 0.$$

So by using (3.2) and (2.7) in (4.6), we get

(4.7) 
$$[2\alpha(W) + \beta(W)]\{\eta(V)\xi - V\} = 0.$$

Remarking that the equation  $\{\eta(V)\xi - V\} = 0$  does not hold for K-contact manifold with respect to quartersymmetric metric connection. So we obtain

(4.8) 
$$[2\alpha(W) + \beta(W)] = 0,$$

which implies that  $2\alpha(W) = -\beta(W)$  got any vector field *W*. Then we state the following:

**Theorem 4.1.** Let *M* be a generalized recurrent K-contact manifold with respect to quarter-symmetric metric connection, then  $2\alpha(W) = -\beta(W)$ .

#### 5. Generalized $\phi$ -recurrent K-contact manifold with respect to the quarter-symmetric metric connection:

We define a Generalized  $\phi$ -recurrent K-contact manifold with respect to the quarter-symmetric metric connection if its curvature tensor  $\tilde{R}$  satisfies the condition

(5.1) 
$$(\widetilde{\nabla}_W \widetilde{R})(U,V)Z = \alpha(W)\widetilde{R}(U,V)Z + \beta(W)\{g(V,Z)U - g(U,Z)V\}$$

where  $\alpha$  and  $\beta$  are 1-form and it is defined by

(5.2) 
$$\alpha(W) = g(W, \rho_1), \ \beta(W) = g(W, \rho_2)$$

where  $\rho_1$  and  $\rho_2$  are vector fields associated with 1-forms  $\alpha$  and  $\beta$  respectively.

Then by virtue of (2.1) and (5.1) can be written in the form

 $(5.3) - (\widetilde{\nabla}_W \widetilde{R})(U, V)Z + \eta ((\widetilde{\nabla}_W \widetilde{R})(U, V)Z)\xi = \alpha(W)\widetilde{R}(U, V)Z + \beta(W)\{g(V, Z)U - g(U, Z)V\}$ from which it follows that

(5.4) 
$$-g\left(\left(\widetilde{\nabla}_{W} \tilde{R}\right)(U, V)Z, U_{i}\right) + \eta\left(\left(\widetilde{\nabla}_{W} \tilde{R}\right)(U, V)Z\right)g(\xi, U_{i}) \\ = \alpha(W)g\left(\tilde{R}(U, V)Z, U_{i}\right) + \beta(W)\{g(V, Z)g(U, U_{i}) - g(U, Z)g(V, U_{i})\}.$$

Let  $e_i$ , i = 1, 2, ..., n be an orthonormal basis of the tangent space at any point of the manifold. Then putting  $U = U_i = e_i$  in (5.4) and taking summation over *i*, then we get

(5.5) 
$$-(\widetilde{\nabla}_W \,\widetilde{S})(V,Z) + \sum_{I=1}^n \eta((\widetilde{\nabla}_W \widetilde{R})(e_i,V)Z)\eta(e_i) = = \alpha(W)\widetilde{S}(V,Z) + (n-1)\beta(W)g(V,Z).$$

The second term of (5.5) it is reduced to

(5.6) 
$$g\left(\left(\widetilde{\nabla}_{W}\,\widetilde{R}\right)(e_{i},V)Z,\xi\right) = g\left(\widetilde{\nabla}_{W}\,\widetilde{R}\,(e_{i},V)Z,\xi\right) - g\left(\widetilde{R}\left(\widetilde{\nabla}_{W}\,e_{i},V\right)Z,\xi\right) - g\left(\widetilde{R}\,(e_{i},V)\widetilde{\nabla}_{W}\,Z,\xi\right).$$

On simplification we obtain,  $g((\tilde{\nabla}_W \tilde{R})(e_i, V)Z, \xi)$ . So then the equation (5.5) can be written in the form

(5.7) 
$$-(\widetilde{\nabla}_W \widetilde{S})(V,Z) = \alpha(W)\widetilde{S}(V,Z) + (n-1)\beta(W)g(V,Z).$$

putting  $Z = \xi$  in the above equation then we get

(5.8) 
$$-(\widetilde{\nabla}_W \widetilde{S})(V,\xi) = \alpha(W)\widetilde{S}(V,\xi) + (n-1)\beta(W)g(V,\xi).$$

S.N. Manjunath Int J Sci Res Sci & Technol. January-February-2022, 9(1) : 558-565 and on simplification we have

(5.9) 
$$(2n-1)g(V,\phi W) - S(V,\phi W) = 2(n-1)\alpha(W)\eta(V) + (n-1)\beta(W)\eta(V)$$

if we put  $V = \phi V$  in the above equation (5.9) then we have

(5.10) 
$$S(\phi V, \phi W) = (2n - 1)g(\phi V, \phi W)$$

and on simplification we have

(5.11)  $S(V,W) = (2n-1)g(V,W) - n\eta(W)\eta(V).$ 

Hence we can state the following:

**Theorem 5.2.** A generalized  $\phi$ -recurrent K-contact manifold with respect to quarter-symmetric metric connection is an  $\eta$ -Einstein manifold.

# 6. C-Bochner Generalized $\phi$ -recurrent K-contact manifold with respect to the quarter-symmetric metric connection

Let us consider a C-Bochner Generalized  $\phi$ -recurrent K-contact manifold with respect to the quartersymmetric metric connection is defined by

(6.1) 
$$\phi^2(\widetilde{\nabla}_W \widetilde{B})(X,Y)Z = \alpha(W)\widetilde{B}(X,Y)Z + \beta(W)[g(Y,Z)X - g(X,Z)Y],$$

where  $\tilde{B}$  is a C-Bochner curvature tensor with respect to the quarter-symmetric metric connection i.e.,

$$\begin{split} (6.2) \qquad \tilde{B}(X,Y)Z &= \tilde{R}(X,Y)Z + \frac{1}{n+3} [g(X,Z)\tilde{Q}Y - \tilde{S}(Y,Z)X - g(Y,Z)\tilde{Q}X + \tilde{S}(X,Z)Y \\ &+ g(\phi X,Z)\tilde{Q}\phi Y - \tilde{S}(\phi Y,Z)\phi X - g(\phi Y,Z)\tilde{Q}\phi X + \tilde{S}(\phi X,Z)\phi Y + 2\tilde{S}(\phi X,Y)\phi Z \\ &+ 2g(\phi X,Y)\tilde{Q}\phi Z + \eta(Y)\eta(Z)\tilde{Q}X - \eta(Y)\tilde{S}(X,Z)\xi + \eta(X)\tilde{S}(Y,Z)\xi - \eta(X)\eta(Z)\tilde{Q}Y] \\ &- \frac{\tilde{D} + n - 1}{n+3} \left[ g(\phi X,Z)\phi Y - g(\phi Y,Z)\phi X + 2g(\phi X,Y)\phi Z \right] + \frac{\tilde{D}}{n+3} \left[ \eta(Y)g(X,Z)\xi \\ &- \eta(Y)\eta(Z)X + \eta(X)\eta(Z)Y - \eta(X)g(Y,Z)\xi \right] - \frac{\tilde{D} - 4}{n+3} [g(X,Z)Y - g(Y,Z)X]. \end{split}$$

Where  $\widetilde{D} = \frac{\widetilde{r}+n-1}{n+1}$ .

Then by virtue of (2.1) and (6.1) then we have

(6.3)  $-(\tilde{\nabla}_W \tilde{B})(X,Y)Z + \eta((\tilde{\nabla}_W \tilde{B})(X,Y)Z)\xi = \alpha(W)\tilde{B}(X,Y)Z + \beta(W)[g(Y,Z)X - g(X,Z)Y].$ Let  $\{e_i, i = 1, 2, ..., n\}$  be an orthonormal basis of the tangent space at any point of the manifold. Then putting  $Y = Z = e_i$  in the above equation and taking summation over *i*, and then by substituting  $U = \xi$  and then by  $X = \xi$  we obtain

$$\beta(W) = -\left[\frac{4}{(n+3)}\right]\alpha(W).$$

Now, we state the following:

**Lemma 6.1.** Let \$M\$ be a C-Bochner generalized \$\phi\$-recurrent \$K\$-contact manifold with respect to quarter-symmetric metric connection then we have

$$\beta(W) = -\left[\frac{4}{(n+3)}\right]\alpha(W).$$

Now, putting  $X = U = e_i$  in (6.3) and taking summation over *i*, and substituting  $Z = \xi$  and on simplification, we get

$$S(Y,W) = Ag(Y,W) + B\eta(Y)\eta(W)$$

where

 $A = \left[\frac{\{(n-1)(2n+5)-r\}}{n+1}\right] \text{ and } B = \left[\frac{\{r-(n-1)(n+4)\}}{n+1}\right].$  We state the following:

**Theorem 6.2.** A C-Bochner generalized \$\phi\$-recurrent K-contact manifold with respect to quarter-symmetric metric connection is an \$\eta\$-Einstein manifold.

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