

Parallel Operation of Modular Single-phase Transformerless Grid-tied PV Inverters with Common DC Bus and AC Bus

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ABSTRACT

In order to eliminate the common-mode (CM) leakage current in the transformer less photovoltaic (PV) systems, the concept of the virtual dc bus is proposed in this paper. By connecting the grid neutral line directly to the negative pole of the dc bus, the stray capacitance between the PV panels and the ground is bypassed. As a result, the CM ground leakage current can be suppressed completely.

Meanwhile, the virtual dc bus is created to provide the negative voltage level for the negative ac grid current generation. Consequently, the required dc bus voltage is still the same as that of the full-bridge inverter. Based on this concept, a novel transformer less inverter topology is derived, in which the virtual dc bus is realized with the switched capacitor technology. It consists of only five power switches, two capacitors, and a single filter inductor. Therefore, the power electronics cost can be curtailed. This advanced topology can be modulated with the unipolar sinusoidal pulse width modulation (SPWM) and the double frequency SPWM to reduce the output current ripple. As a result, a smaller filter inductor can be used to reduce the size and magnetic losses.

Keywords—PV System, Transformerless Inverter, SPWM, Virtual DC bus concept, Operation Modes of the circuit, Hardware Theory

I. INTRODUCTION

The distributed photovoltaic (PV) power generation systems have received increasing popularity in both the commercial and residential areas. In most occasions, the inverters are used to feed the PV power into the utility grid. It is important for the PV inverter to be of high efficiency, due to the relatively high price of the PV panels. Small size is also strongly desired for the low-power and single-phase systems,

especially when the inverters are installed indoor. The word "photovoltaic" combines two terms – "photo" means light and "voltaic" means voltage. A photovoltaic system in this discussion uses photovoltaic cells to directly convert sunlight into electricity. Photovoltaic power generation employs solar panels composed of a number of solar cells containing a photovoltaic material. Materials presently used for photovoltaics include mono crystalline silicon, polycrystalline silicon, amorphous

silicon, cadmium telluride, and copper indium gallium selenide/sulfide. Due to the increased demand for renewable energy sources, the manufacturing of solar cells and photovoltaic arrays has advanced considerably in recent years. Solar photovoltaics is a sustainable energy source where 100 countries are utilizing it. Solar photovoltaics is now, after hydro and wind power, the third most important renewable energy source in terms of globally installed capacity. Installations may be ground mounted or built into the roof or walls of a building. (either building-integrated photovoltaics or simply rooftop).

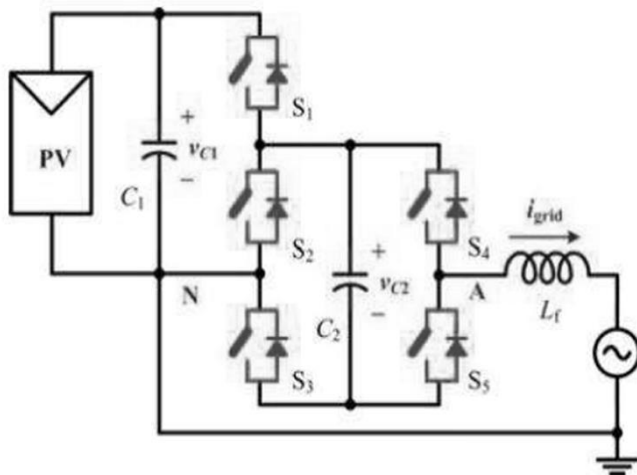
The largest recent shift in inverter technology is the availability of transformer less inverters in the United States.

They have long been popular in Europe, but now most inverter manufacturers have added a transformer less option to their existing inverter line. Without a heavy transformer, they weigh about 50% to 70% less than a transformer-based inverter of similar output, and the size of the inverter housing can be (but isn't always) reduced. Inverter efficiency is also increased there are no longer losses associated with having a transformer to step up the voltage. And because the transformer (which is comprised of copper windings on an iron or steel core) is eliminated, they are less expensive to produce. The majority of inverter manufacturers are now including a transformer less inverter line. Exeltech, Ingeteam, and Solar Edge are few examples. They require the DC wiring to be ungrounded. Because neither the positive nor negative conductor is connected to ground, they must meet more NEC requirements, including the use of PV wire (a double-insulated single conductor cable having added sunlight and mechanical protection) for exposed wires (i.e., module interconnects and exposed home run wiring). Over current protection and disconnect devices are required on both the positive and negative conductors, since they are both ungrounded. Arrays that require the positive conductor be grounded (those using Sun Power modules, for example) are not recommended for use with

transformer less inverters, because the array must be ungrounded. SPWM technique is based on classical SPWM technique with carriers and reference sine waveform. Only difference between them is, in digital SPWM a sine table consisting of values of sine waveform sampled at certain frequency is used. As a result reference waveform in digital SPWM represents a sample and hold waveform of sine waveform. A simple comparator with a sawtooth carrier can turn a sinusoidal command into a pulse-width modulated output. In general, the larger the command signal, the wider the pulse as shown in Fig. Output stays high as long as the command is greater than the carrier. Pulse-width modulation (PWM), as it applies to motor control, is a way of delivering energy through a succession of pulses rather than a continuously varying (analog) signal. By increasing or decreasing pulse width, the controller regulates energy flow to the motor shaft. The motor's own inductance acts like a filter, storing energy during the "on" cycle while releasing it at a rate corresponding to the input or reference signal. In other words, energy flows into the load not so much the switching frequency, but at the reference frequency. The energy of each push is stored in the inertia of the heavy platform, which accelerates gradually with harder, more frequent, or longer-lasting pushes. The riders receive the kinetic energy in a very different manner than how it's applied.

Virtual DC bus Concept: The positive pole of the virtual bus is connected to the ground point N, so that the voltage at the midpoint C is either zero or $-V_{dc}$. The dotted line in the figure indicates that this connection may be realized directly by a wire or indirectly by a power switch. With points B and C joined together by a smart selecting switch, the voltage at point A can be of three different voltage levels, namely $+V_{dc}$, zero, and $-V_{dc}$. Since the CM current is eliminated naturally by the structure of the circuit, there is not any limitation on the modulation strategy, which means that the advanced modulation technologies such as the unipolar SPWM

or the double-frequency SPWM can be used to satisfy various PV applications.



Grid Tie Inverter: Inverters take DC power and invert it to AC power so it can be fed into the electric utility company grid. The grid tie inverter must synchronize its frequency with that of the grid (e.g. 50 or 60 Hz) using a local oscillator and limit the voltage to no higher than the grid voltage. A high-quality modern GTI has a fixed unity power factor, which means its output voltage and current are perfectly lined up, and its phase angle is within 1 degree of the AC power grid. The inverter has an on-board computer which will sense the current AC grid waveform, and output a voltage to correspond with the grid. However, supplying reactive power to the grid might be necessary to keep the voltage in the local grid inside allowed limitations. Otherwise, in a grid segment with considerable power from renewable sources voltage levels might rise too much at times of high production, i.e. around noon. Grid-tie inverters are also designed to quickly disconnect from the grid if the utility grid goes down. This is an NEC requirement that ensures that in the event of a blackout, the grid tie inverter will shut down to prevent the energy it transfers from harming any line workers who are sent to fix the power grid. Properly configured, a grid tie inverter enables a home owner to use an alternative power generation system like solar or wind power without extensive rewiring and without batteries. If the alternative power being produced is insufficient, the

deficit will be sourced from the electricity grid. The proposed topology can also work with double-frequency SPWM to achieve a higher equivalent switching frequency. In the double-frequency SPWM, the five power switches are separated into two parts, and are modulated with two inverse sinusoidal waves respectively. S_1 , S_2 , and S_3 are modulated with u_{g1} , while S_4 and S_5 are modulated with u_{g2} . During the positive half grid cycle, the circuit rotates in the sequence of "state 4 – state 1 – state 2 – state 1," and the output voltage v_{AN} varies between $+V_{dc}$ and the zero with twice of the carrier frequency. During the negative half grid cycle, the circuit rotates in the sequence of "state 4 – state 3 – state 2 – state 3," and the output voltage v_{AN} varies between $-V_{dc}$ and zero. The aforementioned two modulation strategies both have their own advantages. The double-frequency SPWM can provide a higher equivalent switching frequency so that the size and weight of the filter inductor can be reduced. On the other hand, the unipolar SPWM can guarantee that the virtual dc bus C_2 is charged by the real bus every switching cycle, so that the current stress on S_1 and S_3 caused by the operation of the switched capacitor can be reduced. In this paper, the unipolar SPWM is chosen as an example for the performance evaluation and experimental verification. For all of the four operation states, there is no limitation on the direction of the output current i_{grid} , since the power switches with antiparallel diodes can achieve bidirectional current flow. Therefore, the proposed topology has the capability of feeding reactive power into the grid to help support the stability of the power system. The proposed topology is also immune against transient overvoltage of the grid. During the mains positive voltage spikes, the voltage at point A is clamped at V_{dc} by C_1 and the antiparallel diodes of S_1 and S_4 . Similarly, during the negative voltage spikes, the voltage at point A is clamped at $-V_{dc}$ by C_2 and the antiparallel diodes of S_2 and S_5 . Therefore, the mains transient over voltage does not pose a safety threat for the inverter. A

simulation design modulation technique as shown in Fig.1 & Fig.4 is implemented in MATLABSIMULINK with the help of pulse generators where the Unipolar & Double polar frequency is varied (Fig.2 & Fig.5). A modified circuit of the system i.e. a Unipolar and Double polar frequency Grid Tie inverter is also designed which is shown in Fig 1 & 7. The THD analysis is also compared for all the three simulations which is shown below in Fig 3 & 6.

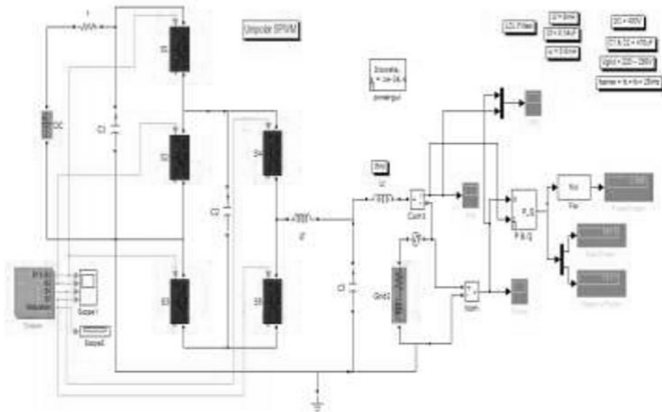


Fig. 1. Proposed Unipolar Frequency Grid Tie Inverter

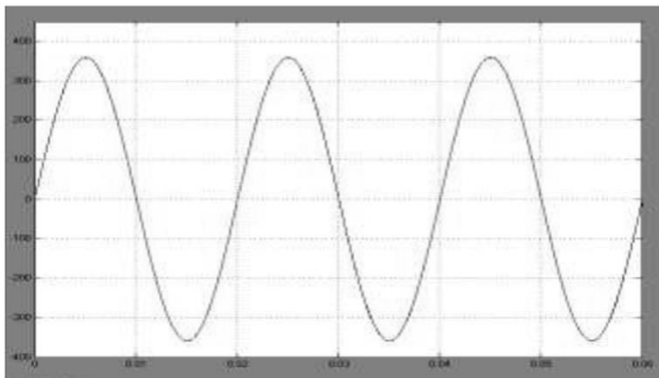


Fig. 2. Output Voltage Waveform

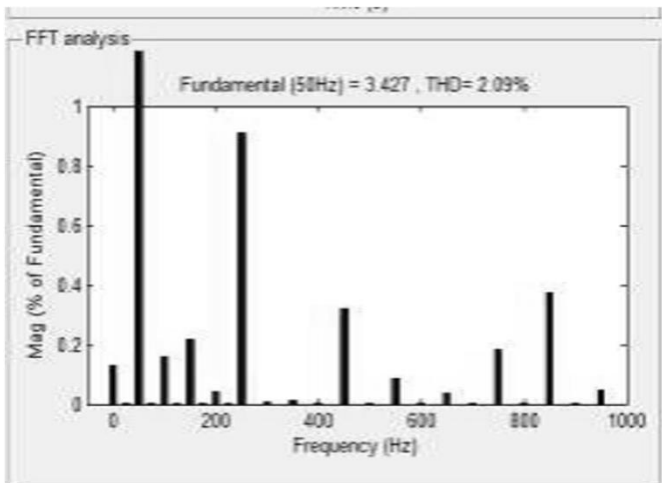


Fig. 3. O/P Current Distortion

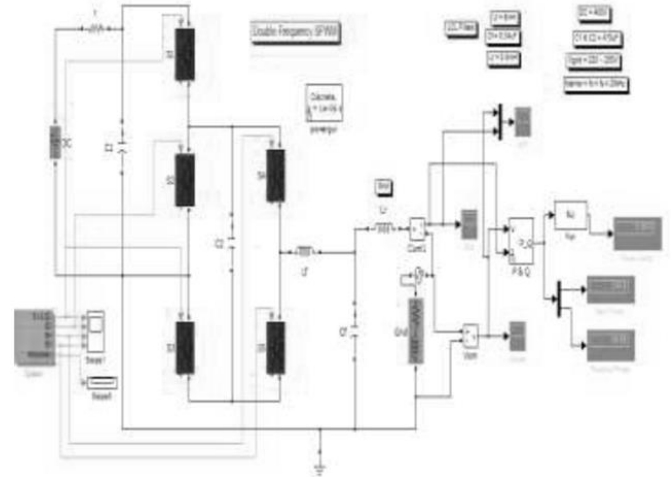


Fig. 4 Proposed Double SPWM GTI



Fig. 5. O/P Double SPWM Voltage Waveform

The concept of the virtual dc bus is depicted. By connecting the grid neutral line directly to the negative pole of the PV panel, the voltage across the parasitic capacitance C_{PV} is clamped to zero. This prevents any leakage current flowing through it. With respect to the ground point N, the voltage at midpoint B is either zero or $+V_{dc}$, according to the state of the switch bridge. The purpose of introducing the virtual dc bus is to generate the negative output voltage, which is necessary for the operation of the inverter. If a proper method is designed to transfer the energy between the real bus and the virtual bus, the voltage across the virtual bus can be kept the same as the real one. The positive pole of the virtual bus is connected to the ground point N, so that the voltage at the midpoint C is either zero or $-V_{dc}$. The dotted line in the figure indicates that this connection may be

realized directly by a wire or indirectly by a power switch. With points B and C joined together by a smartselecting switch, the voltage at point A can be of three different voltage levels, namely $+V_{dc}$, zero, and $-V_{dc}$. Since the CM current is eliminated naturally by the structure of the circuit, there is not any limitation on the modulation strategy, which means that the advanced modulation technologies such as the unipolar SPWM or the double-frequency SPWM can be used to satisfy various PV applications.

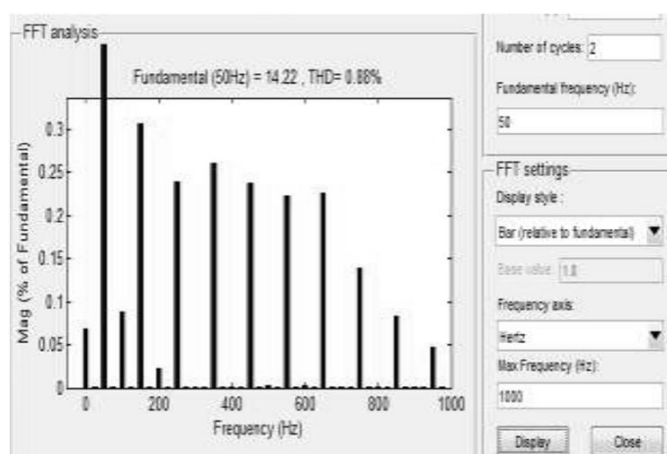


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II. DERIVED TOPOLOGY AND MODULATION STRATEGY

Based on the virtual dc bus concept, a novel inverter topology is derived as an example to show the clear advantages of the proposed methodology. It consists of five power switches $S1-S5$ and only one single filter inductor L_f . The PV panels and capacitor $C1$ form the real dc bus while the virtual dc bus is provided by $C2$. With the switched capacitor technology, $C2$ is charged by the real dc bus through $S1$ and $S3$ to maintain a constant voltage. This topology can be modulated with the unipolar SPWM and double-frequency SPWM. The detailed analysis is introduced as follows.

Unipolar SPWM: The waveform for the unipolar SPWM of the proposed inverter is displayed. The gate drive signals for the power switches are generated according to the relative value of the modulation wave u_g and the carrier wave u_c . During the positive half grid cycle, $u_g > 0$. $S1$ and $S3$ are turned ON and $S2$ is turned OFF, while $S4$ and $S5$ commute complementally with the carrier frequency. The capacitors $C1$ and $C2$ are in parallel. During the negative half cycle, $u_g < 0$. $S5$ is turned ON and $S4$ is turned OFF. $S1$ and $S3$ commute with the carrier frequency synchronously and $S2$ commutates in complement to them. The circuit rotates between states 3 and 2. At state 3, $S1$ and $S3$ are turned OFF while $S2$ is turned ON. The negative voltage is generated by the virtual dc bus $C2$ and the inverter output is at negative voltage level. At state 2, $S1$ and $S3$ are returned ON while $S2$ is turned OFF. The

inverter output voltage v_{AN} equals zero; meanwhile, C_2 is charged by the dc busthrough S_1 and S_3 . Double-Frequency SPWM The proposed topology can also work with doublefrequency SPWM to achieve a higher equivalent switching frequency, as shown in Fig. 9. In the double-frequency SPWM, the five power switches are separated into two parts, and are modulated with two inverse sinusoidal waves respectively. S_1, S_2 , and S_3 are modulated with u_{g1} , while S_4 and S_5 are modulated with u_{g2} . During the positive half grid cycle, the circuit rotates in the sequence of “state 4 – state 1 – state 2 –state 1,” and the output voltage v_{AN} varies between $+V_{dc}$ and the zero with twice of the carrier frequency. During the negative half grid cycle, the circuit rotates in the sequence of “state 4 – state 3 – state 2 –state 3,” and the output voltage v_{AN} varies between $-V_{dc}$ and zero. and the circuit rotates between states 1 and 2.

During the negative half cycle, $u_g < 0$. S_5 is turned ON and S_4 is turned OFF. S_1 and S_3 commutate with the carrier frequency synchronously and S_2 commutates in complement to them. The circuit rotates between states 3 and 2. At state 3, S_1 and S_3 are turned OFF while S_2 is turned ON. The negative voltage is generated by the virtual dc bus C_2 and the inverter output is at negative voltage level. At state 2, S_1 and S_3 are returned ON while S_2 is turned OFF. The inverter output voltage v_{AN} equals zero; meanwhile, C_2 is charged by the dc busthrough S_1 and S_3 . Double-Frequency SPWM The proposed topology can also work with doublefrequency SPWM to achieve a higher equivalent switching frequency, as shown in Fig. 9. In the double-frequency SPWM, the five power switches are separated into two parts, and are modulated with two inverse sinusoidal waves respectively. S_1, S_2 , and S_3 are modulated with u_{g1} , while S_4 and S_5 are modulated with u_{g2} . During the positive half grid cycle, the circuit rotates in the sequence of “state 4 – state 1 – state 2 –state 1,” and the output voltage v_{AN} varies between $+V_{dc}$ and the zero with twice of the carrier frequency. During the negative half grid cycle, the circuit rotates in the

sequence of “state 4 – state 3 – state 2 –state 3,” and the output voltage v_{AN} varies between $-V_{dc}$ and zero.

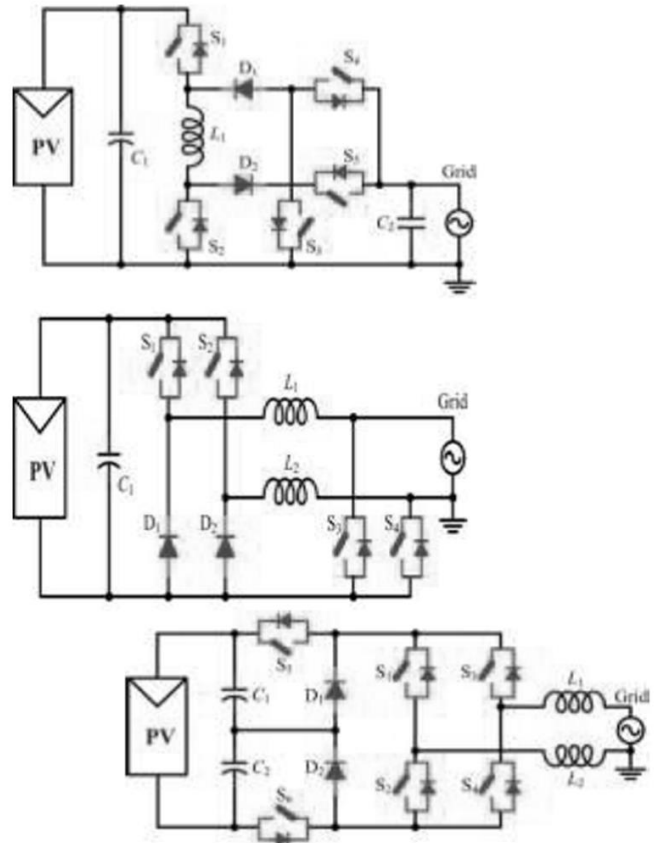


Fig.7. SVPWM Modulation

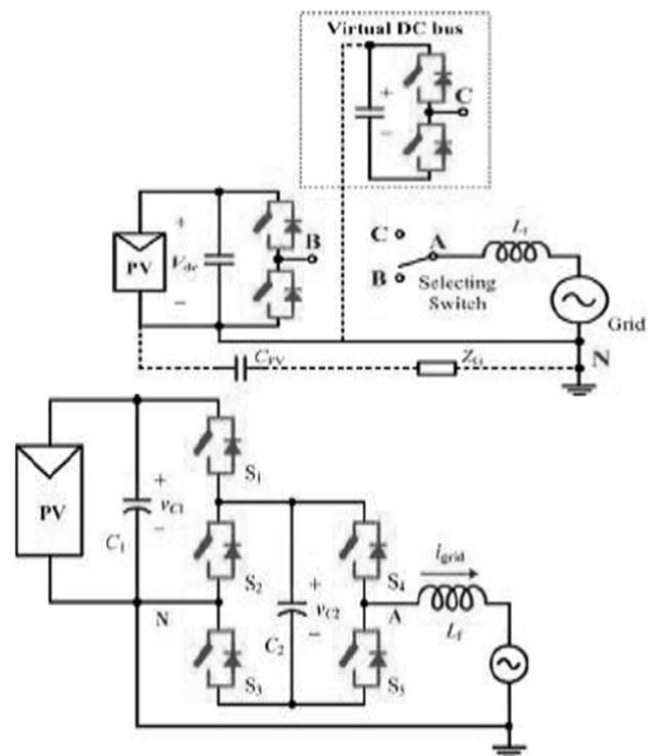


Fig.8. SVPWM Modulation

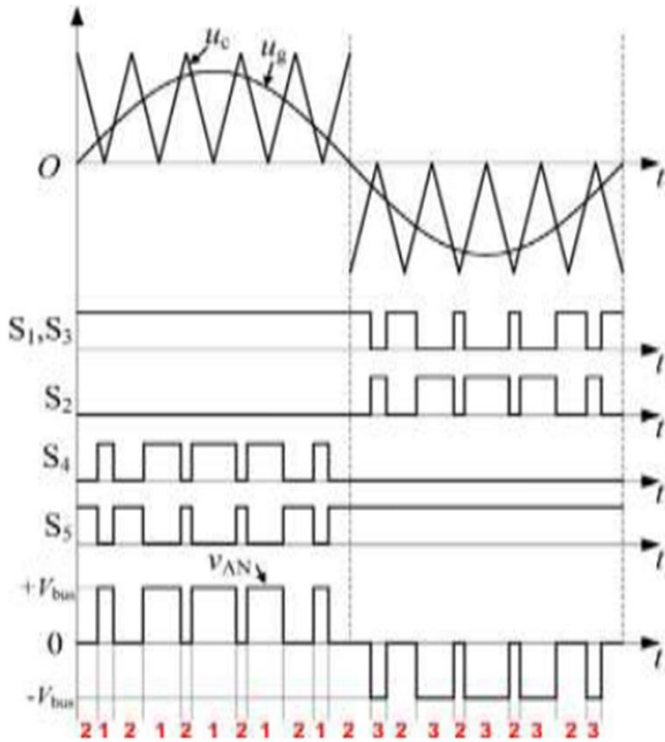


Fig 9. Unipolar Waveform

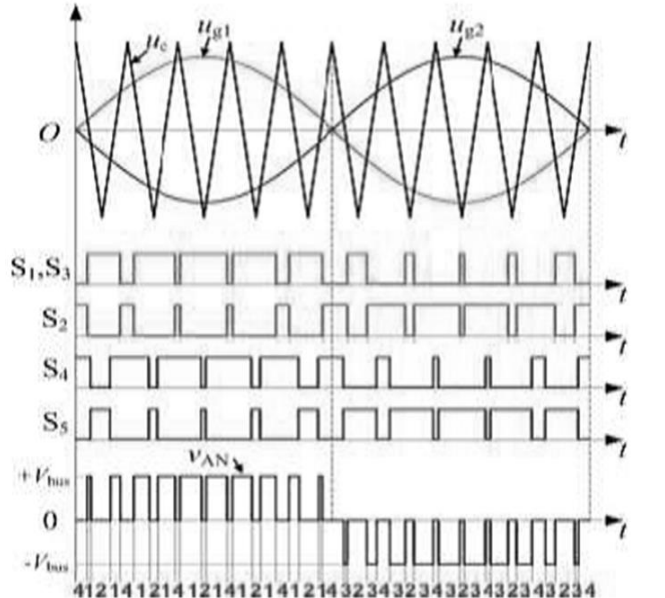


Fig 10. Double Frequency SPWM

The aforementioned two modulation strategies both have their own advantages. The double-frequency SPWM can provide a higher equivalent switching frequency so that the size and weight of the filter inductor can be reduced. On the other hand, the unipolar SPWM can guarantee that the virtual dc bus C2 is charged by the real bus every switching cycle, so that the current stress on S1 and S3 caused by

the operation of the switched capacitor can be reduced. In this paper, the unipolar SPWM is chosen as an example for the performance evaluation and experimental verification. For all of the four operation states, there is no limitation on the direction of the output current *i_{grid}*, since the power switches with antiparallel diodes can achieve bidirectional current flow. Therefore, the proposed topology has the capability of feeding reactive power into the grid to help support the stability of the power system. The proposed topology is also immune against transient overvoltage of the grid. During the mains positive voltage spikes, the voltage at point A is clamped at V_{dc} by C1 and the antiparallel diodes of S1 and S4. Similarly, during the negative voltage spikes the voltage at point A is clamped at -V_{dc} by C2 and the antiparallel diodes of S2 and S5. Therefore, the main transient overvoltage does not pose a safety threat for the inverter.

Switching Losses: During the positive half cycle, only two switches, namely S4 and S5, commute at the carrier frequency, so the switching losses are the same as the traditional full-bridge inverter. During the negative half cycle, S1, S2, and S3 commute at the carrier frequency. Although the number of high-frequency switches increases to 3, it can be seen from the following analysis that the switching losses almost keep the same.

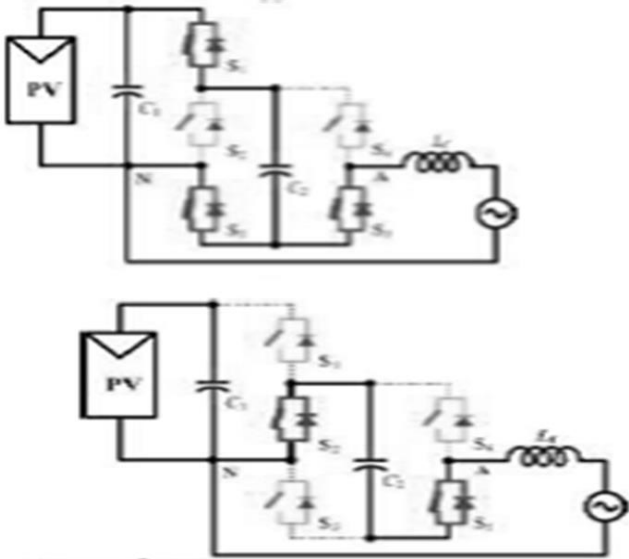


Fig 11

III. CONCLUSION

This review has covered some of the standards that inverters for PV and grid applications must full fill, which focus on power quality injection of dc current to the grid, detection of islanding operation, and system grounding. The demands stated by the PV modules have also been reviewed. The role of power decoupling between the modules and the grid has been investigated. An important result is that the amplitude of the ripple across a PV module should not exceed 3V in order to have a utilization efficiency of 98% at full generation. Finally the basic demands defined by the operator have also been addressed, such as low cost, high efficiency, and long life time. The next part of the review was a historical summary of the solutions used in the past, where large areas of PV modules were connected to the grid by means of centralized inverters. This included many shortcomings for which reason the string inverters emerged. A natural development was to add more strings, each with an individual dc-dc converter and MPPT, to the common dc-ac inverter, thus, the multi-string inverters were brought to light. This is believed to be one of the solutions for the future. Another trend seen in this field is the development of the ac module, where each PV module is interfaced to the grid with its own dc-ac inverter.

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